

# **DESIGN AND IMPLEMENTATION OF AUTOMATIC PHASE CHANGER**

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## **ABSTRACT**

Simulation of an Automatic Phase Changer (APC) circuit was performed in this project. The simulation was carried out using Proteus 8. Automatic Phase Changer (APC) automatically changes the phase as the name suggests. In three phase power system 3 inputs of APC circuit are connected to three phases of the system and its three outputs are connected to three different loads. These three loads always need their normal rated voltage for proper operation. Results observed that if voltage of any phase goes below the nominal rating the loads may malfunction. Here, Automatic Phase Changer comes into action. When a phase voltage goes below its nominal rating, APC provides correct level of voltage to the load connected to that phase.

**KEYWORDS:** Relay, Switch, Comparator, Phase Changer, Automatic

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*To my Loved Ones*

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# **CHAPTER 1**

## **Introduction**

### **1.1 Introduction**

Power instability and phase failure has become a serious problem in the developing countries like Bangladesh and Nigeria to improve their socio economic condition [2]. Almost all of the companies; Industrial, commercial and also domestic loads are run by the public power supply which associates different problems for example: imbalances among the phases, phase failure or sometimes complete power shut down occurs due to various types of technical problems occurred in the power generation, transmission and distribution system [3]. Most of the power consumers use single phase equipment for operational purpose which is greatly affected if there is unbalance voltages, under voltages or over voltages. A significant amount of time would be required for manual switch over operation and as a result, serious trouble could be associated with the machines or in the production process. Moreover, a standby manpower would always be required to change over the supply voltage line. To overcome these challenges, Automatic phase changing system could be implemented. Here, an Automatic Phase Changer circuit has been simulated.

### **1.2 Advantage over Traditional Method**

Automatic phase changer finds wide application in modern world. During earlier days, if there was any power failure in any one of three phases occurs, it was required to switch to the available phase manually. By implementing automatic phase changer it automatically shifts to the phase where correct voltage is available. It can be used in residences, small offices, buildings etc. Automatic phase changer is a circuit of very compact design. This circuit is very cost effective. It is very easy to install too. Low maintenance is required for this circuit.

### **1.3 Objective of this Work**

In three-phase applications, if low voltage is occurred in any one or two phases then to maintain normal voltage for the equipment this circuit can play an effective role. However, a proper-rating fuse needs to be used in the input lines (R, Y and B) of each phase. The circuit provides correct voltage in the same power supply lines through relays from the other phase where correct voltage is available.

### **1.3.1 Primary objectives**

The primary objective is to make the automatic phase changer circuit which will work for under voltage fault in a three phase system and to show that by using this circuit, intensity & amplitude of voltage in the load side will remain the same before the fault occur.

### **1.3.2 Secondary Objectives**

The secondary objective is to show the simulation & to prove theoretically that the automatically phase change circuit actually works for over voltage fault.

## **1.4 Overview of this Project**

Chapter 2 discusses about the circuit diagram and explains the working principle of the Automatic Phase Changer (APC). Chapter 3 discusses about the main components used in the APC circuit. Simulation and its results are discussed in chapter 4. Chapter 5 discusses about main part of our project – implementation and results. Results are shown in tables. In the final chapter conclusion, the limitations of this circuit and future scopes are mentioned.

## CHAPTER 2

### Modeling of Automatic Phase Changer

#### 2.1 Necessity of Automatic Phase Changer

In three phase power supply line voltage can be dropped or risen from the rated voltage supplied in any phase for various causes. The reasons for voltage fluctuation are discussed below in brief.

**Voltage rise:** In case of transmission line is charged on no load- due to its capacitive effect (Ferranti effect) voltage gets rise at receiving end more than that rated voltage.

**Voltage drop:** Due to active power loss or resistance of the line, IR drop occurs which result in getting less voltage at the receiving end which is less than the rated voltage. Another reason for voltage drop is that if heavy load is applied all of a sudden, voltage drop occurs.

Automatic Phase Changer circuit can provide nominal voltage to the emergency loads with the help of healthy line. In the next portion, the principle of circuit operation is going to be described.

#### 2.2 Circuit Description and Analysis

It is possible to supply current of correct voltage level in all the phases with this through relays if proper voltage is available in any phase. Using it all the equipment can be operated smoothly when correct voltage is available on a single phase in the building. The circuit is made mainly using a comparator, transformer, transistor and relay. Three identical sets of the circuit, one each for three phases, are used.

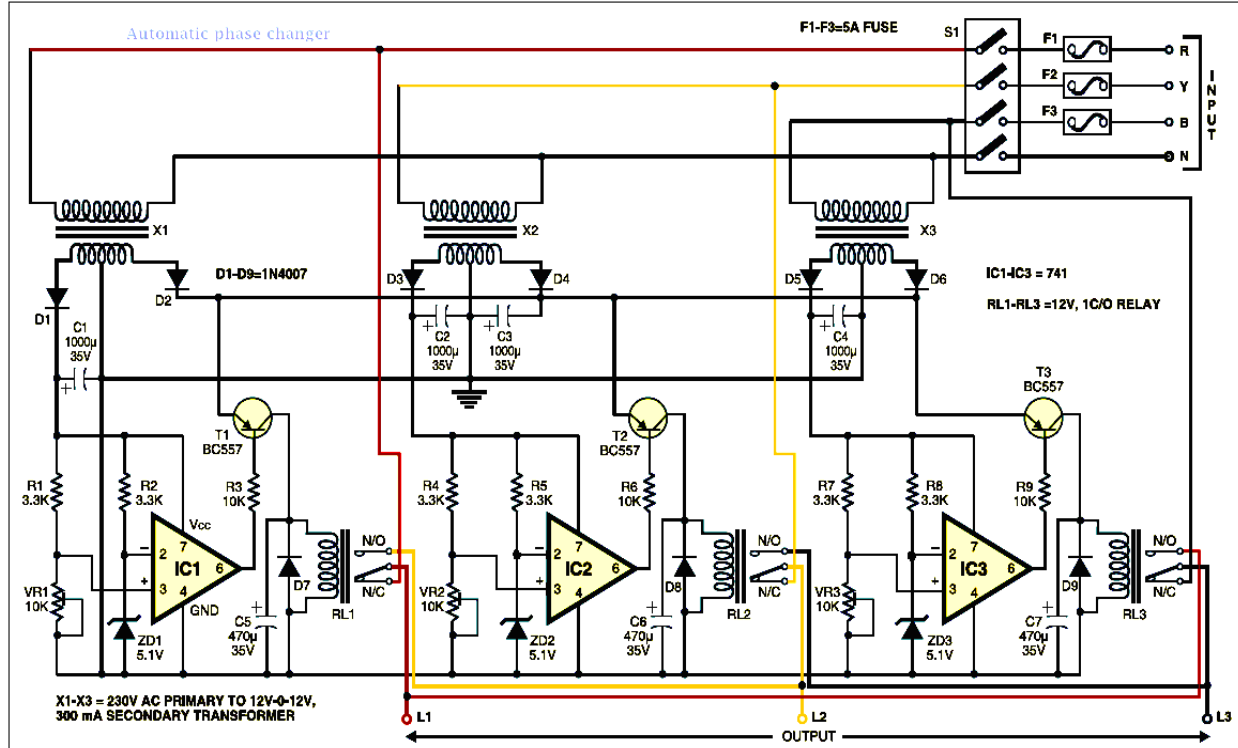


Figure 2. 1: Automatic Phase Changer. [3]

From Figure 2.1, when 120V is given to the input side of each of the transformers X1, X2 and X3. It turns in 12Vdc in the output side of the transformers. The diodes D1, D2, D3, D4, D5, and D6 are used here to rectify the sinusoidal signal to dc signal. In this circuit seven capacitors (C1, C2, C3, C4, C5, C6, and C7) are used. Capacitor C1, C2, C3, and C4 makes the output signal of transformer smooth to make exact 12V dc. Whereas other capacitors (which are connected to relay in parallel) make some delay to connect the correct line to load safely through relay. When the 12V dc voltage goes across R1 resistor some voltage gets dropped. In this circuit IC1, IC2 and IC3 work as comparator; those are 741 Op-amps. The voltage taken from the voltage divider circuit of resistor R1 and preset resistor VR1; where, VR1 is used to set the reference voltage according to the requirement is applied at non-inverting pin 3 of operational amplifier IC1. The reference voltage at inverting pin 2 is fixed to 5.1V through a zener diode ZD1. The voltage at non-inverting pin 3 remains high at the normal condition. So the output of the comparator remains 12 V. As a result the pnp transistor remains off. When any of the input phase voltage gets below 120 V the voltage in pin 2 gets high then the non-inverting pin 3 and the output of the comparator goes low. As a result the pnp transistor starts conducting current and relay RL1 energizes and load L1 is

disconnected from phase 'R' and connected to phase 'Y' through relay RL2. Similarly, the auto phase-change of the remaining two phases 'Y' and phase 'B' can be explained.

## 2.3 Block Diagram

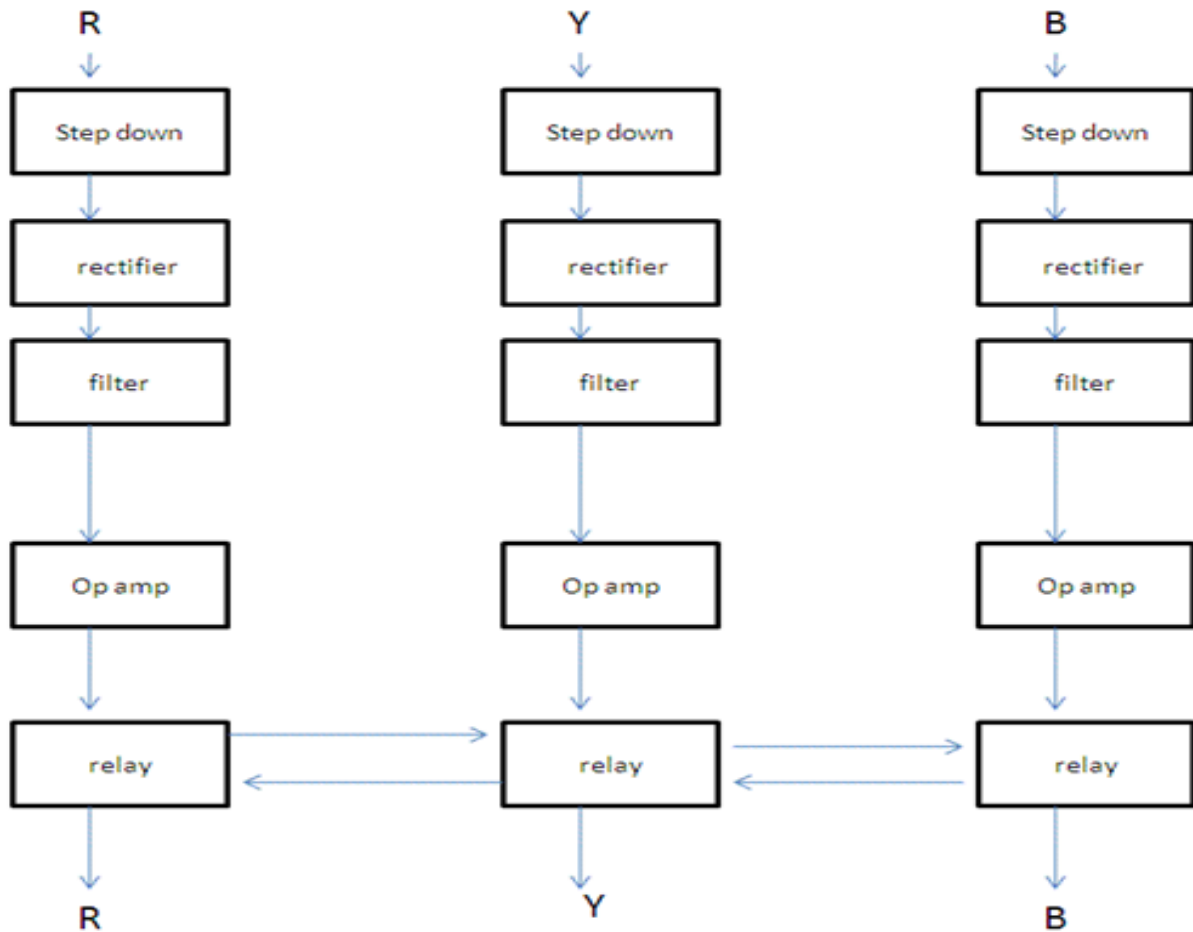


Figure 2. 2: Block Diagram of Automatic Phase Changer. [4]

There are 3 phases 'R', 'Y' and 'B' in three phase power supply line. From the block diagram of Figure 2.2, step down transformer steps down the phase voltage at level which can be used for biasing the electronic circuit. Then the voltage gets rectified and filtered by using diode and capacitor to get smooth dc voltage. The voltage then bias the Op-Amp which works as a

comparator. Op-Amp senses the problem and activates or deactivates the relay. So, the phase which voltage is below the 120 V gets connected to the other stabilized phase voltage by the relay. And the whole system gets stabilized.

## **2.4 Summary**

After simulating the whole circuit one or two phase voltages have been changed from the three phase power supply and equal load voltages was obtained in the output. In the next chapter, it will be described about the components used in the circuit.



## CHAPTER 3

### Main Components Feature

#### 3.1 Introduction

In this chapter it will be discussed about Diode, Zener Diode, BJT, Op-amp, characteristic and properties of Op-amp, Practical Op-amp circuit, Op-amp as comparator, Transformer, step- up and step down transformer, Relay, working principle of relay and their specific work in the circuit.

#### 3.2 Diode

A Diode is an electronic component with two-terminals and asymmetric conductance; it has low resistance to current flow in one direction, and high resistance in the other. The semiconductor diode is created by simply joining an n-type and p-type material together, just the joining of one material with a majority carrier of electrons to one with a majority carrier of holes. Diodes are physically very small in size and control small current up to about 100mA. Diodes generally have a silver or black band at one end of their body to help identify which end is its cathode terminal. Figure 3.1 shows a diode.

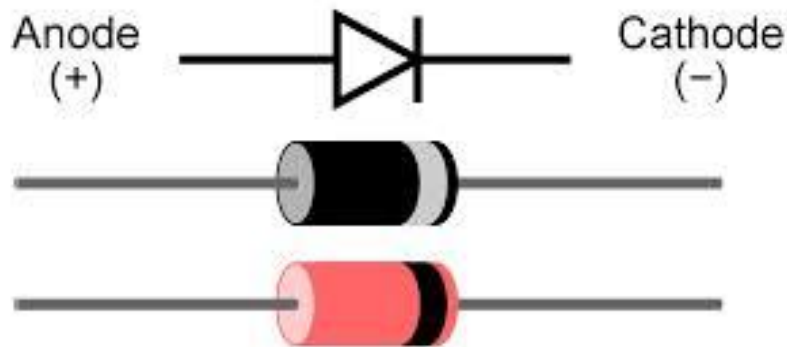


Figure 3. 1: Diode [5]

To obtain forward bias or “on” condition it is needed to be applied positive potential to the p-type material and the negative potential to the n-type material. Forward bias refers to the application of voltage across the device such that the electric field at the junction is reduced. The

arrow in the symbol of diode points in the direction of conventional current flow through the diode. That mean the diode will only conduct if a positive supply is connected to the Anode (A) terminal and a negative supply is connected to the Cathode (K) terminal, thus only allowing current to flow through the forward direction only. Forward bias will act like a short circuit switch. Figure 3.2 shows the diode in forward bias condition.

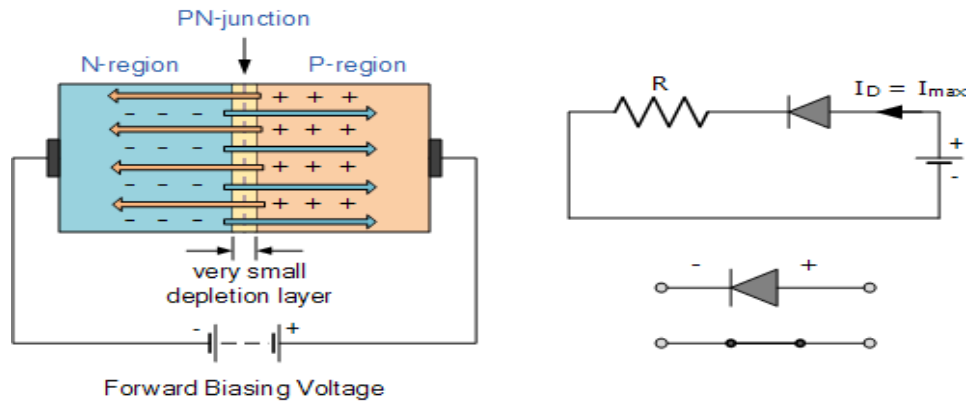


Figure 3. 2: Diode in Forward Bias Condition [7]

If an external potential of  $V$  volts is applied across p-n junction such that the positive terminal is connected to the n-type material and the negative terminal is connected to the p-type material. In reverse bias the diode will block any current flowing through it and instead will act like an open switch. Figure 3.3 shows diode reverse bias condition.

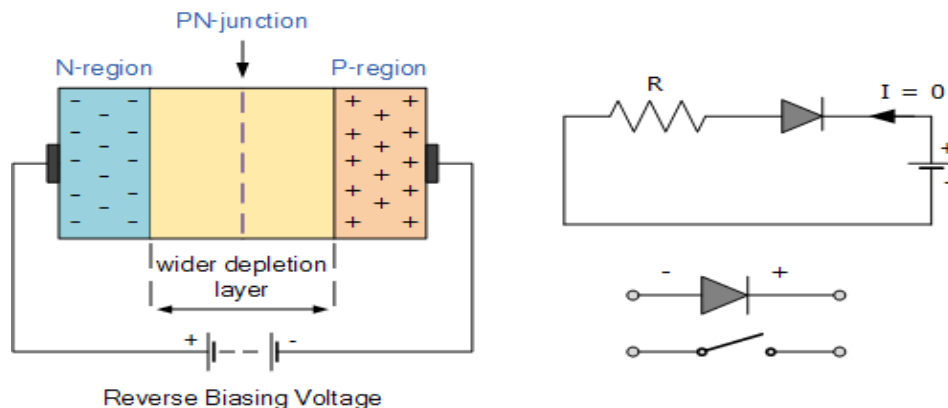


Figure 3. 3: Diode in Reverse Bias Condition [7]

Diodes will block any and all current flowing into the reverse direction, or just act like a short circuit if current flow is forward. The most important diode characteristic is its current-voltage ( $I$ - $V$ ) relationship. Figure 3.4 shows the  $I$ - $V$  characteristic curve of diode. This defines what the

current running through a component is, given what voltage is measure across it. Silicon Diode has a very high value of reverse resistance and gives a forward voltage drop of about 0.6-0.7V. They have fairly low values of forward resistance giving them high peak value of forward current and reverse current. Germanium diode has a forward voltage drop of about 0.2-0.3V. I-V curve of a diode is entirely non-linear.

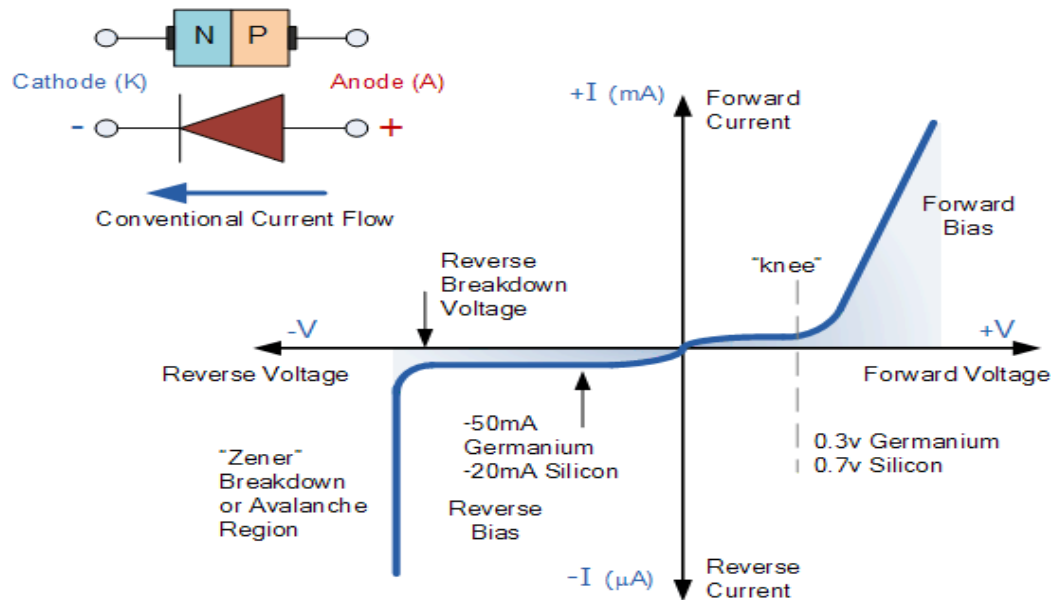


Figure 3. 4: Diode Characteristics [5]

### 3.3 Zener Diode

A Zener diode is a type of diode that permits current not only in the forward direction like a normal diode, but also in the reverse direction if the voltage is larger than the breakdown voltage known as "Zener knee voltage" or "Zener voltage". Zener Diode is a diode operates in reverse bias at Peak Inverse Voltage (PIV) called the Zener voltage. Common Zener Voltage is 1.8V to 200V. Figure 3.5 shows a Zener diode.

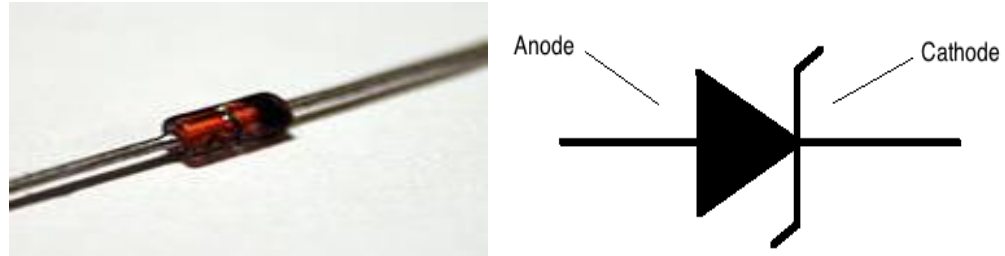


Figure 3. 5: Zener Diode [5]

### 3.3.1 Zener Region

- The Diode is in the reverse biased condition.
- At some point the reverse biased voltage is so large the diode breaks down.
- The reverse current increases dramatically.
- This maximum voltage is called avalanche breakdown voltage & the current is called avalanche current. Figure 3.6 shows the Zener Region.

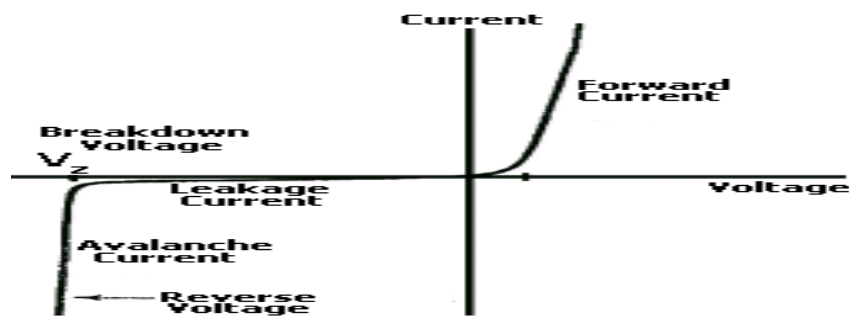


Figure 3. 6: Zener Regions [5]

### 3.4 BJT

A Bipolar Junction Transistor (BJT) is a kind of transistor which operates through the contact of two types of semiconductor. BJT s can be used as amplifier, switch or in oscillators. BJT has three terminal connections to three doped semiconductor region. BJT is a three layer semi-conductor device consisting of either two n-type or one p-type layer of material or two p-types and one n-type layer of material. The former is called an NPN transistor and the latter is called PNP transistor. In an NPN transistor, a thin and lightly doped p-type material is sandwiched between two thicker n-type materials. While in a PNP transistor, a thin and lightly doped n-type material is sandwiched between two thick p-type materials. Figure 3.7 shows NPN and PNP transistor.

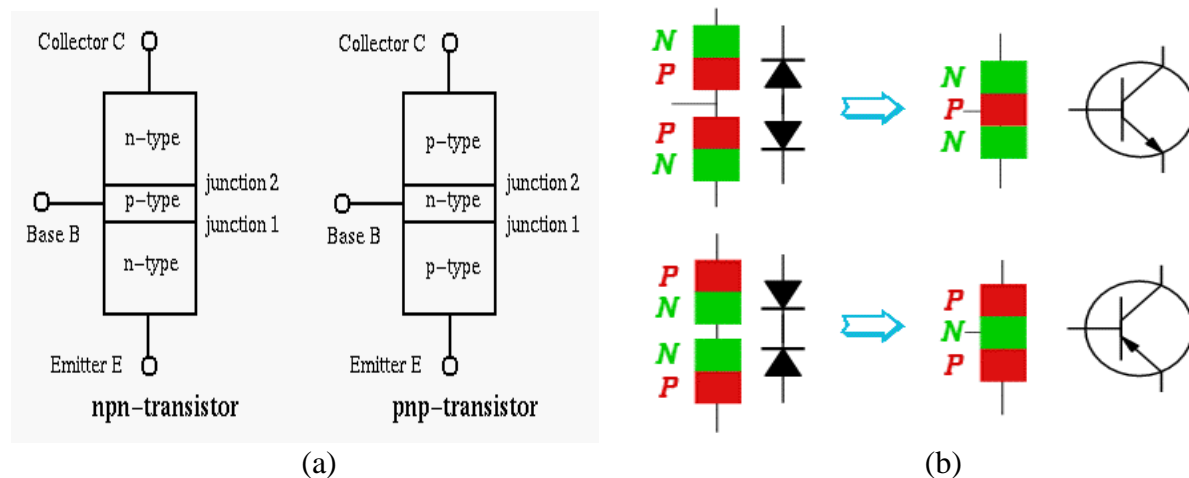


Figure 3. 7: BJT [5]

#### 3.4.1 PNP Transistor

- The majority carriers in the emitter p-type material are holes.
- The base-emitter junction is forward biased to the majority carriers and the holes cross the junction and appear in the base region.
- The base region is very thin and is only lightly doped with electrons so although some electron-hole pairs are formed, many holes are left in the base region.

- The base-collector junction is reverse biased to electrons in the base region and holes in the collector region, but forward biased to holes in the base region; these holes are attracted by the negative potential at the collector terminal.

A large proportion of the holes in the base region cross the base-collector junction into the collector region, creating a collector current; conventional current flow is in the direction of holes movement. Figure 3.8 shows a PNP transistor.

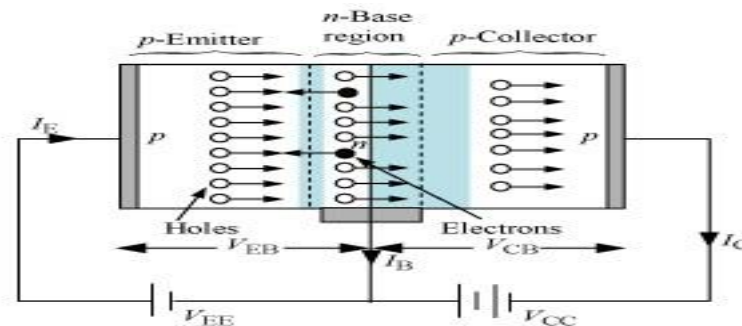


Figure 3. 8: PNP Transistor [10]

### 3.4.2 NPN Transistor

- The majority carriers in the n-type emitter material are electron.
- The base-emitter junction is forward biased to these majority carriers and electron cross the junction and appears in the base region.
- The property of base region is that it is very thin having lightly doped with holes, As a result, a portion of recombination is occurred with holes but many electrons are found in the base region.
- The base collector junction is reverse biased to hole in the base region and electrons in the collector region, but is forward biased to electron in the base region, these electron are attracted by the positive potential at the collector terminal.
- A large proportion of the electrons in the base region cross the base-collector junction into the collector region, creating a collector current. Figure 3.9 shows a NPN transistor.

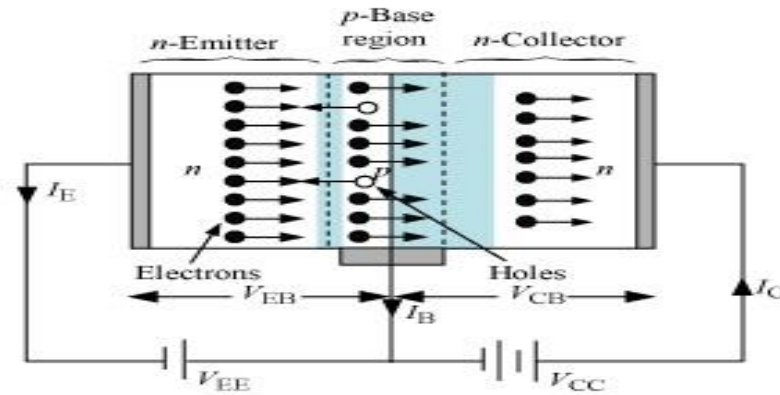


Figure 3. 9: NPN Transistor [9]

### 3.5 Operational Amplifier

An operational amplifier or op-amp is a high gain differential amplifier with high input impedance and low output impedance. Op-amp is used to provide voltage amplitude changes (amplitude & polarity), oscillator, filter circuit, comparator & many types of instrumentation circuit. An op-amp contains a number of differential amplitude stages to achieve a very high voltage gain. An operational amplifier is a DC coupled high gain electronic voltage amplifier with a differential input and, usually a single ended output. An op-amp produces an output voltage that is typically hundreds of thousands times larger than the voltage difference between its input terminals. Figure 3.10 shows a 741 IC.

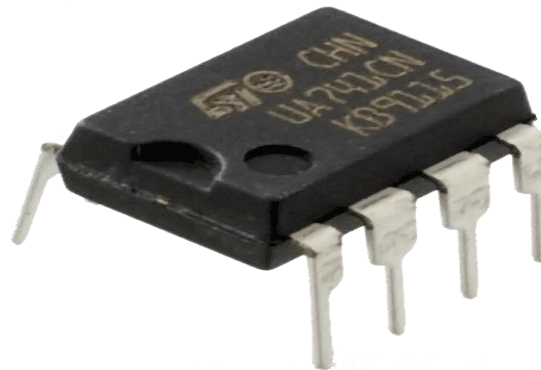


Figure 3. 10: 741 IC [5]

Among the available integrated circuit, operational amplifier is probably the most versatile. It is very cheap especially keeping in mind the fact that it contains several hundred components. The most common Op-amp is the 741 & it is used in much circuit. The op-amp is a linear amplifier with an amazing variety of uses. Its main purpose is to amplify a weak signal. The 741 integrated circuit looks like any other 'chip'. However, it is a general purpose OP-AMP. It is required only to know the basic information about its operation and use. The diagram opposite shows the pins of the 741 OP-AMP. The important pins are 2, 3 and 6 because these represent inverting, non-inverting and voltage out. Notice the triangular diagram that represents an Op-Amp integrated circuit. Figure 3.11 shows the pin configuration of 741 IC.

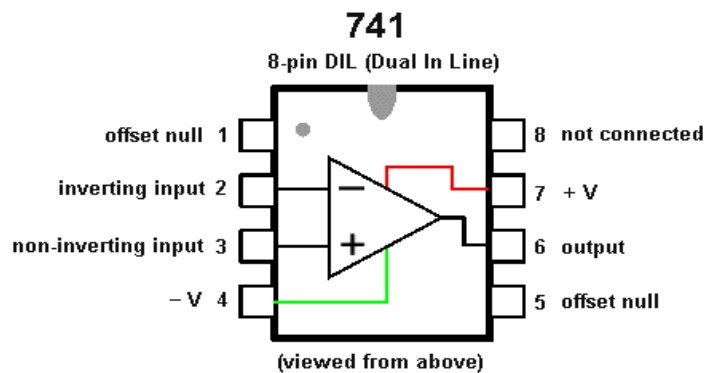


Figure 3. 11: Pin Configuration of 741 IC [6]

### 3.5.1 Characteristic of an ideal Op-amp (741IC)

- Infinity gain.
- Infinity Bandwidth.
- Infinity Input impedance (between the two input terminals and from each terminal to ground).
- Infinity output current drive capabilities.
- Zero output impedance.
- Zero input voltage offset.
- Zero input current.
- Common Mode Rejection Ratio (CMRR).
- The Slew Rate.



### 3.5.2 Properties of an ideal Op-amp (741IC)

- Infinite Open Loop gain
  - The gain without feedback
  - Equal to differential gain
- Infinite Input impedance
  - Input current is almost 0A
  - m-A input current in low-grade op-amp
- Zero Output Impedance
  - act as perfect internal voltage source
  - No internal resistance
  - Output impedance in series with load
  - Reducing output voltage to the load
  - Practically,  $R_{out} \sim 20-100 \text{ } \Omega$

### 3.5.3 Practical Op-amp Circuit

For having various operating characteristics, op-amp can be connected in a large number of circuits. In this section, it will be covered few of the most common of these circuit connections.

#### 3.5.3.1 Voltage Follower (Buffer)

The voltage follower circuit, as shown in figure 3.12, provides a gain of unity (1) with no polarity or phase reversal. From the equivalent circuit (figure 3.12) it is clear that

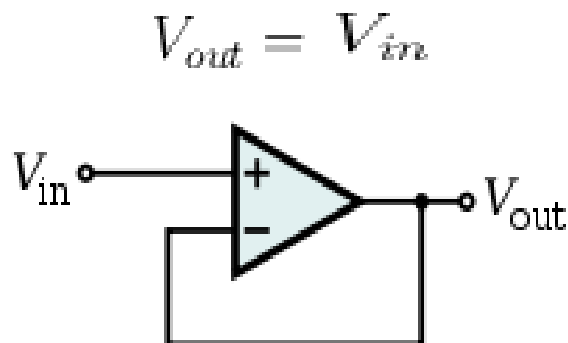


Figure 3. 12: Voltage Follower [14]

### 3.5.3.2 Inverting Amplifier

The most widely used constant-gain amplifier is inverting amplifier, as shown in figure 3.13. The output is obtained by multiplying the input by a fixed or constant gain, set by the input resistor  $R_1$  and feedback resistor  $R_f$ . This output also being inverted from the input. We can write,

$$V_{out} = -\frac{R_f}{R_1} V_{in}$$

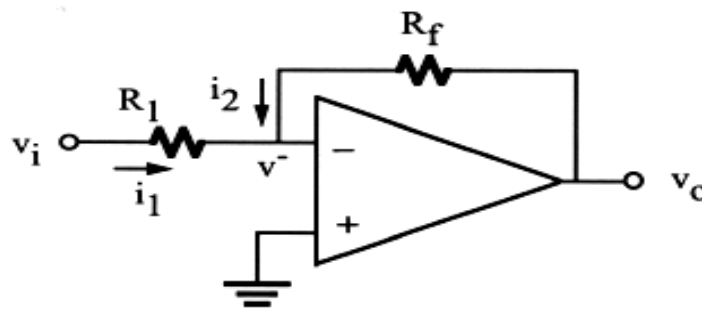


Figure 3. 13: Inverting Amplifier [5]

### 3.5.3.3 Non-inverting Amplifier

The connection of figure 3.14 has shown an op-amp circuit that works as a non-inverting amplifier or constant –gain multiplier. The voltage across  $R_1$  is  $V_{in}$ . This must be equal to the output voltage, through a voltage divided of  $R_1$  and  $R_2$ . The resulting relation will be

$$V_{out} = V_{in} \left( 1 + \frac{R_2}{R_1} \right)$$

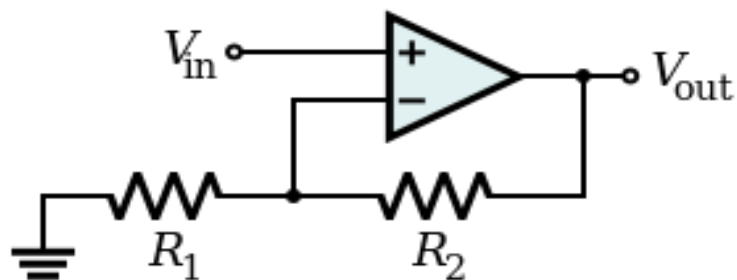


Figure 3. 14: Non-inverting Amplifier [5]

### 3.5.3.4 Summing Amplifier

Probably the most used of the op-amp is the summing amplifier circuit shown in figure 3.15. The circuit shows a three input summing amplifier circuit. We can express the output voltage in terms of the input as

$$V_{out} = -R_f \left( \frac{V_1}{R_1} + \frac{V_2}{R_2} + \cdots + \frac{V_n}{R_n} \right)$$

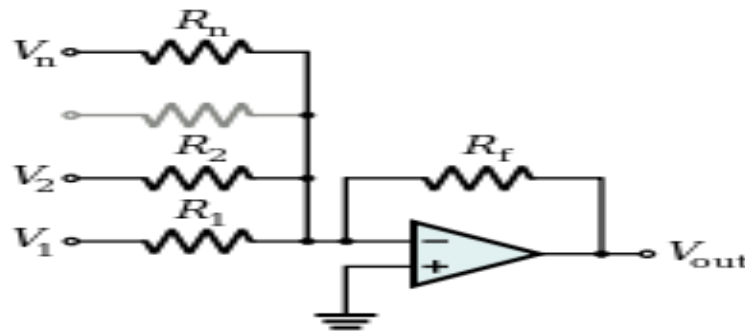


Figure 3. 15: Summing Amplifier [11]

### 3.5.3.5 Comparator

A comparator is an electronic device which is used to compare two voltage or current and sends a digital signal as output indicating which one is larger. The result of this comparator is indicated by output voltage. Owing to its extremely large open-loop gain, op-amp has become an extremely sensitive device for verifying its input with zero. In figure 3.16 if  $V_1 > V_2$  the output is driven to the positive supply voltage and if  $V_2 < V_1$  it is driven to the negative supply voltage. The switching time for - to + is limited by the slew rate of the op-amp. Figure 3.16 has shown a comparator.

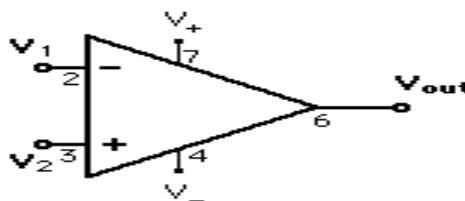


Figure 3. 16: comparator [15]

### 3.6 Using 741 Op-amp as a comparator

There are several reasons to use op-amps as comparators. Some are technical, one is purely economic. Op-amps are manufactured as single devices, but also as duals and quads, two or four op-amps on a single chip. Duals and quads are less costly and require less space on the board resulting in a more economical solution. It is economical to use the spare op-amp in a quad as a comparator rather than buying an additional comparator, but this is not a good design practice. For clean fast switching, comparators are desired but often these have worse dc parameters than many op-amps. So it may be convenient to use an op-amp as a comparator in applications requiring low  $V_{os}$ , low  $I_B$ , and wide CMR. Where high speed is important, it is never recommended to use an op-amp as a comparator. 741 IC can be used as a comparator and an amplifier. The difference between the two is small but significant. Even if used as a comparator the 741 still detects weak signals so that they can be recognized more easily. A comparator is such a circuit in which two input voltages are compared. One voltage is called the reference voltage ( $V_{ref}$ ) and the other is called the input voltage ( $V_{in}$ ). A comparator may be the perfect solution in which case two voltage signals are to be compared and need to be distinguished which one is stronger. As the basic building block is also formed by it which one is required for non-sinusoidal waveform generators or relaxation oscillators, in regarding over relaxation oscillators it deserves priority. We have studied that when the op-amp is used in open-loop configuration (or without feedback) any input signal (differential or single) which even slightly exceeds zero drives the output into saturation because of very high open-loop voltage gain (nearly infinity) of op-amp. It means that the application of a small differential input signal of appropriate polarity causes the output to switch to its either saturation. Thus op-amp comparator is a circuit with two inputs and one output. The two inputs can be compared with each other i.e. one of them can be considered a reference voltage,  $V_{ref}$ .

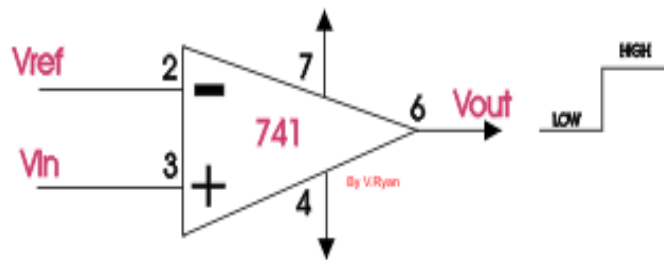


Figure 3. 17: Op-amp comparator circuit [15]

Figure 3.17 shows a 741 op-amp comparator circuit. When  $V_{in}$  rises above or falls below  $V_{ref}$  the output changes polarity (+ becomes -). Positive is sometimes called HIGH. Negative is sometimes called LOW.[15]

### 3.7 Transformer

Transformer is an electrical device which is used to change the voltage level of ac electrical through magnetic field action. It consists of two or more coils of wire wrapped around a common ferromagnetic core. These coils are not directly connected. The only connection is when the coils are the common magnetic flux present within the core. A constant-voltage transformer (Figure 3.18) consists essentially of three parts: the primary coil which carries the alternating current from the supply lines, the core of magnetic material in which is produced an alternating magnetic flux, and the secondary coil in which is generated an EMF by the change of magnetism in the core which it surrounds. Sometimes, transformer consists of only one winding, which acts as both primary and secondary coils. The high-tension winding is composed of many turns of relatively fine copper wire, well insulated to withstand the voltage impressed on it. The low-tension winding is composed of relatively few turns of heavy copper wire capable of carrying considerable current at a low voltage.

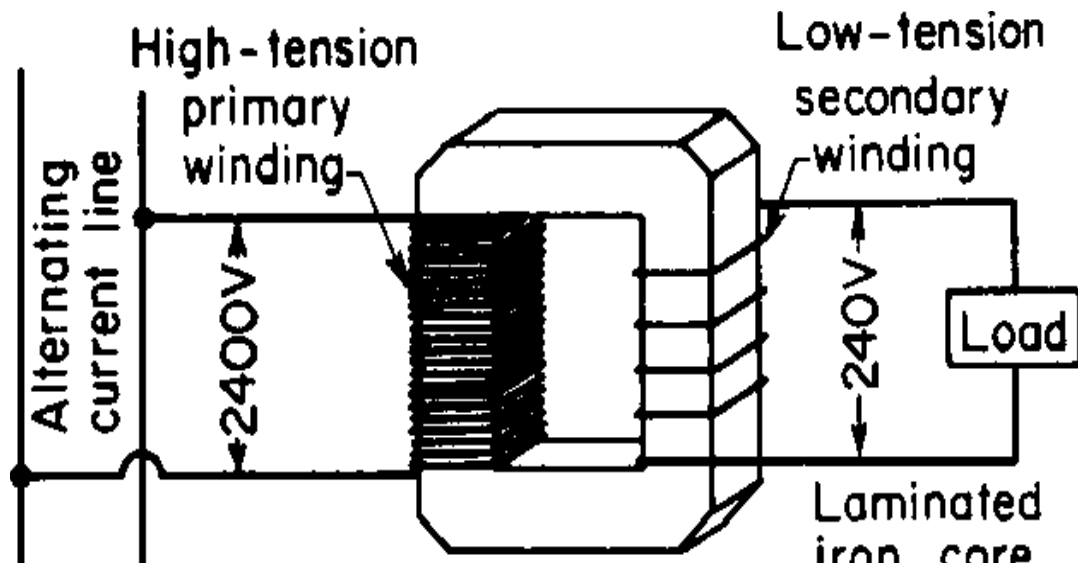


Figure 3. 18: Transformer [16]

The primary winding is the winding of the transformer which is connected to the source of power. It may be either the high- or the low voltage winding, depending upon the application of the transformer. Power is delivered to the load through the secondary winding of the transformer. It may be either the high- or the low-voltage winding, depending upon the application of the transformer. Windings are wound upon the core which acts as a magnetic circuit. The high-tension winding is the one which is rated for the higher voltage. The low-tension winding is the one which is rated for the lower voltage.

### 3.7.1 Transformer cores

All transformer cores are made up of stacks of sheet-steel punching firmly clamped together. Figure 3.19 showing one method of assembling and clamping of the sheets. Sometimes the laminations are coated with a thin varnish to reduce eddy- current losses. When the laminations are not coated with varnish, a sheet of insulating paper is inserted between lamination at regular intervals. Figure 3.19 shows a transformer core.

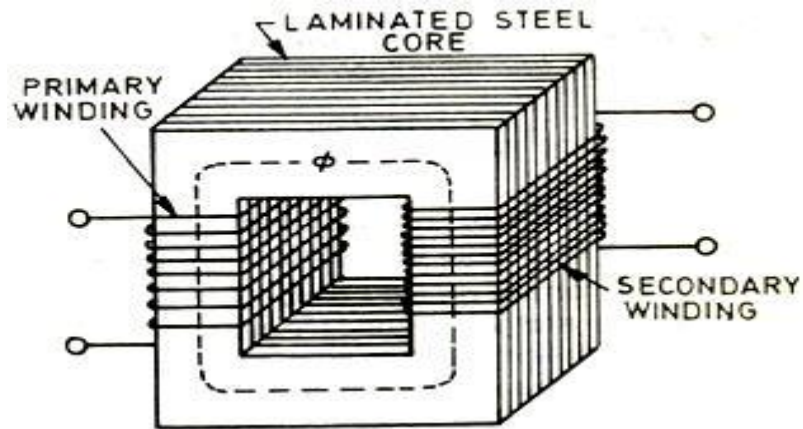


Figure 3. 19: Transformer core [16]

In the new type of core construction a continuous strip of silicon steel is consisted. This core is wounded by insulated coils and this is tightly fixed using spot welding at the end. These types of construction reduce the cost of manufacture and reduce the power loss in the core due to eddy-currents.

### 3.7.2 Classification of transformer

- According to method of cooling
  - Self-air-cooled (dry type)
  - Air-blast-cooled (dry type)
  - Liquid-immersed, self-cooled
  - Oil-immersed, combination self-cooled and air-blast
  - Oil-immersed, water-cooled
  - Oil-immersed, forced-oil-cooled
  - Oil-immersed, combination self-cooled and water-cooled
- According to insulation between windings
  - Windings insulated from each other
  - Autotransformers
- According to number of phases
  - Single-phase
  - Poly-phase

- According to method of mounting
  - Pole and platform
  - Subway
  - Vault
  - Special
- According to purpose
  - Constant-voltage
  - Variable-voltage
  - Current
  - Constant-current
- According to service
  - Large power
  - Distribution
  - Small power

### **3.7.3 Step-up transformer**

A step-up transformer is used to higher up voltage level from primary to secondary. On a step-up transformer there are more turns on the secondary coil than the primary coil. A step-up transformer increased input voltage in a circuit. A transformer is simple passive device created from wound coils of wire on two separate circuits.

Construction it with fewer wire coil on the output as compared to the input, the output voltage is increased proportionally. Figure 3.20 shows a step-up transformer.



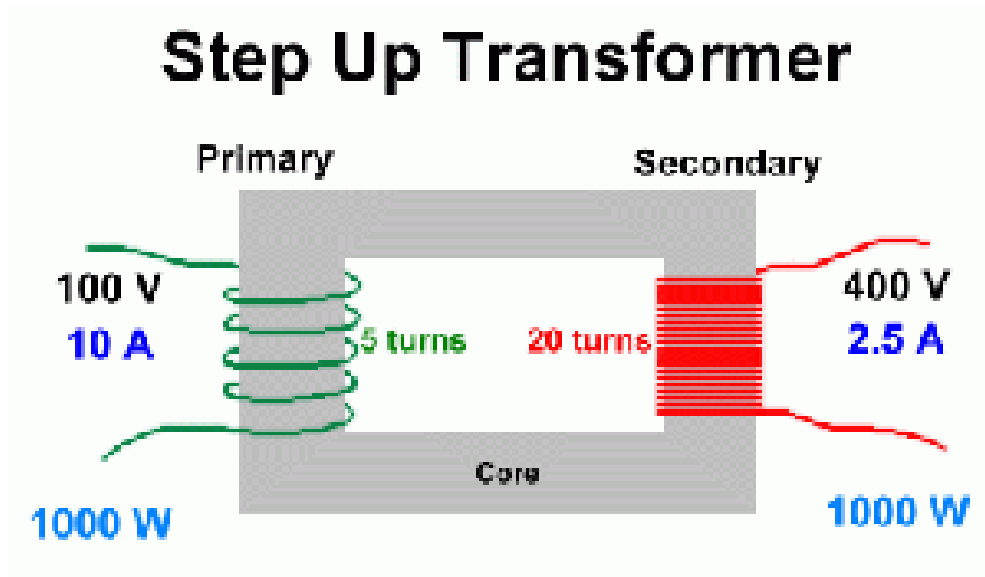


Figure 3. 20: Step-up Transformer [17]

### 3.7.4 Step-down Transformer

A step-down transformer has less turns on the secondary coil than the primary coils. The induced voltage across the secondary coil is less than the applied voltage across the primary coil or in other words the voltage is “stepped-down”. When a transformer’s secondary voltage is lower than the primary voltage, the transformer is called step-down transformer. This type of transformer steps down the voltage exposed to it. A step-down transformer is one so connected that the delivered voltage is less than that supplied, the actual transformer may be the same in one case as in the other.

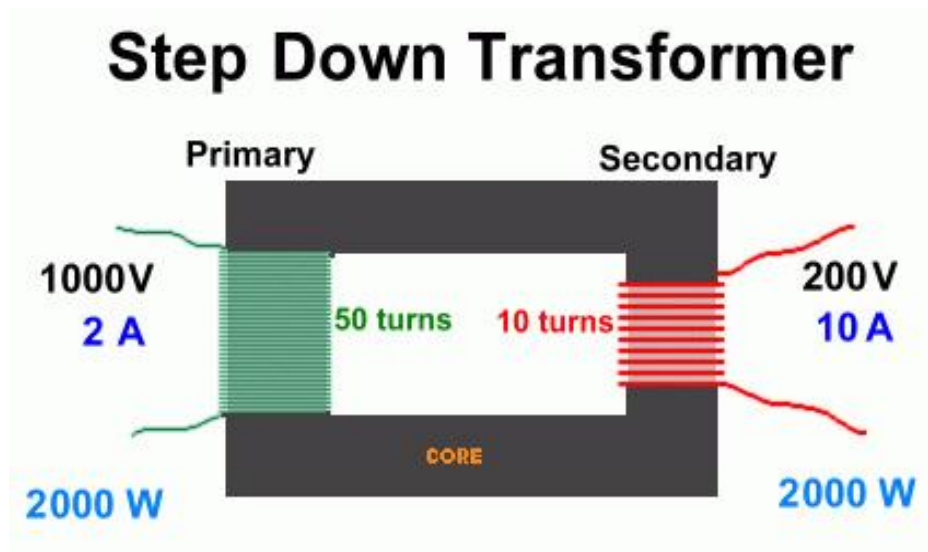


Figure 3. 21: Step-down transformer [18]

Figure 3.21 shows a step-down transformer. Step-down transformers are designed to reduce electric voltage. Their primary voltage is greater than their secondary voltage, this kind of transformer “step down” the voltage applied to it. For instance, a step down transformer is required to use 110V equipment in a country where 220V is the usual supply. A step down transformer converts electrical voltage from one level or phase configuration usually down to lower level. They can include feature for electrical isolation, power distribution, and control & instruction applications. Step-down transformers are made from two or more coils of insulated wire wound around a core made of iron. When voltage is fed to the primary coil, the iron core gets magnetized thus a voltage is induced in the other coil. The turn ratio of the two set of winding determines the amount of voltage transformation.

### 3.8 Relay

A relay is an electrically operated switch. Relay is special switch designed to allow a small circuit to control a large circuit. These devices use a solenoid to control a heavy-duty switch. The wiring for the solenoid may require only 0.5amp to activate, while the switch it controls carries 10 to 30 amps. This device allows the high-current devices to keep localized in one place; this is good for added fire safety and keeping dangerous voltage current as far away from people as possible. Many relay use an electromagnet to operate a switching mechanism mechanically, but other operating principles are also used. Relay are used where it is necessary to control a circuit by a low-power

signal or where several circuits must be controlled by one signal. The first relays were used in long distance telegraph circuit, repeating the signal coming from one Circuit and re-transmitting it to another. Figure 3.22 show a relay.



Figure 3. 22: Relay [19]

### 3.8.1 Pin Configuration of Relay

A relay can be divided into two parts: input and output. Figure 3.23 show the pin configuration of an electric relay. The input section has a coil which generates magnetic field when a small voltage from an electric circuit is applied. This voltage is called the operating voltage. Commonly used relay are available in different configuration of operating voltages like 6V, 9V, 12V, 24V etc. the output section consist of contactors which connected or disconnected mechanically. In a basic relay there are three contacts: normally open (NO), normally close (NC) and common (COM). During no input state, the COM keeps connected to NC. When the operating voltage is applied the relay coil gets energized and COM changes contact to NO. By using proper combination of contactors, the electrical relay can be switched on and off.

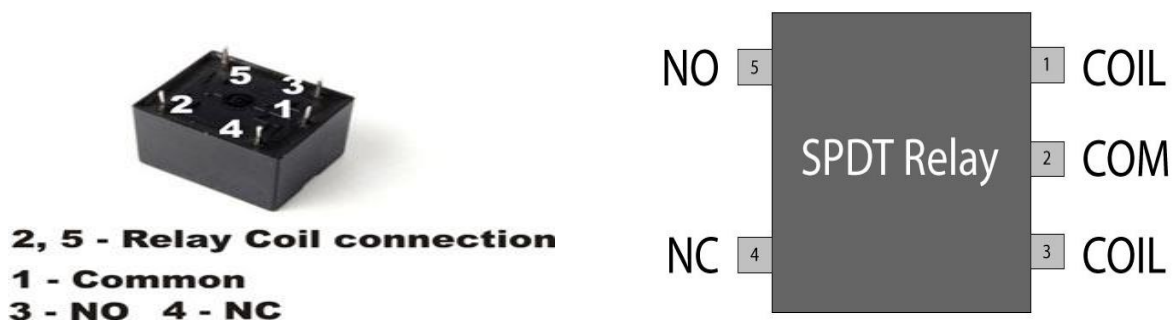


Figure 3. 23: Pin configuration of Relay [20]

### 3.8.2 Working principle of Relay

The working principle of a relay can be better understood by explaining the figure 3.24 given below

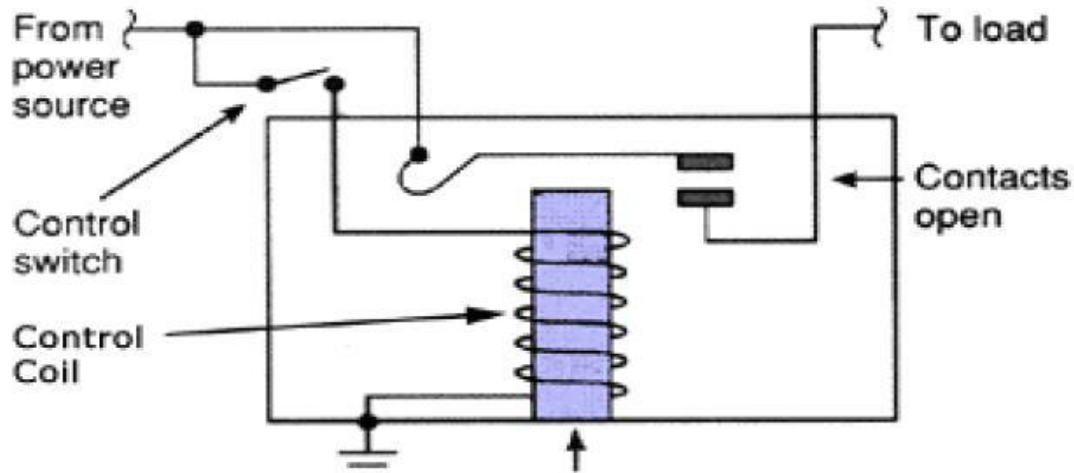


Figure 3. 24: Relay Design [20]

The Figure 3.24 shows an inner section diagram of a relay. An iron core is surrounded by a control coil. As shown, the electromagnet is connected to the power source using a control switch and via contacts to the load. When current starts flowing through the control coil, the electromagnet starts energizing and thus intensifies the magnetic field. In this way, the upper contact arm begins to be attracted across the lower fixed arm and thus the contacts get closed which cause a short circuit for the power to the load. On the other hand, if the relay was already de-energized when the contacts were closed, then the contact move oppositely and make an open circuit. When the coil current supply is off, the movable armature will be moved back to the original position by a force. This force will be almost equal to half the strength of the magnetic force. This force is mainly provided by two factors. They are the spring and also gravity. Relays are mainly made for two basic operations; low voltage and high voltage application. For low voltage applications, more preference will be given to reduce the noise of the whole circuit. For high voltage applications, they are mainly designed to reduce a phenomenon called arcing.

### 3.9 Specific work of Transformer, Diode, Capacitor, Zener Diode, Op-amp, BJT and Relay in the main circuit

- **Transformer:**

The main power supply of any phase is stepped down by a 120V AC primary to 12V-0-12V, 300mA secondary step-down transformer to deliver 12V, 300mA which gives the operating voltage of the op-amp.

- **Diode:**

The main power supply is stepped down by the transformer to deliver 12V, 300mA, which is rectified by the diode. The diode chops of the negative voltage and gives a 12V dc output. Figure 3.25 has shown the diode rectification.

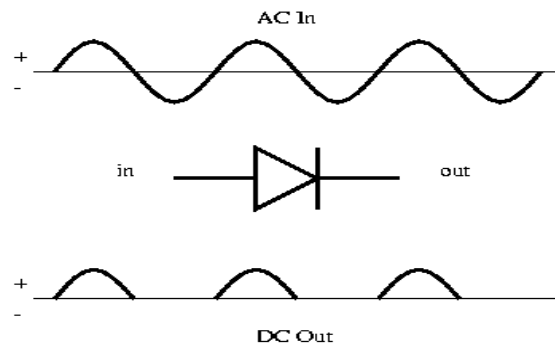


Figure 3. 25: Diode Rectification

- **Capacitor:**

The capacitor will work as a filter. It will filter the 12V dc output and give smoother 12V dc output. Figure 3.26 shows capacitor acting as a filter.

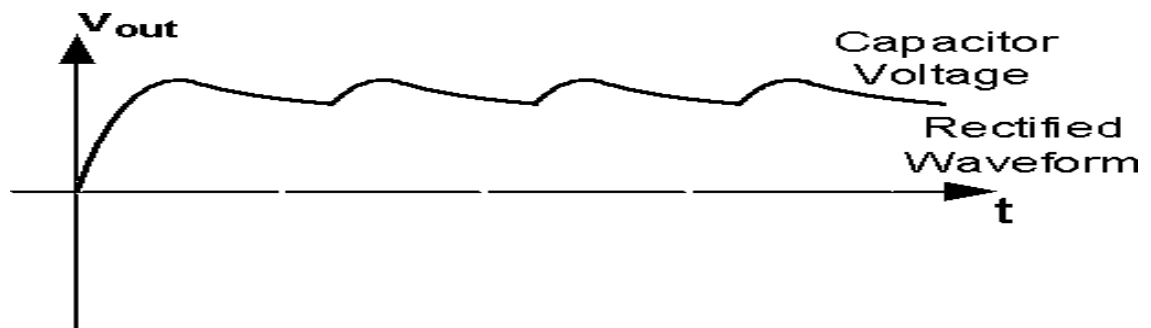


Figure 3. 26: Capacitor acting as a filter.

- **Op-amp:**

The 741 op-amp will work as a comparator. It will compare the voltage in pin 2 & pin 3. The voltage at non-inverting pin 3 of the op-amp is taken from the voltage divider circuit of resistor R1 and preset resistor VR1 of the variable resistor. The reference voltage at inverting pin 2 is fixed to 5.1V through zener diode. Till the supply voltage in one phase is 120V the voltage at non-inverting pin 3 will be higher than 5.1V at the reference voltage at pin 2, then the output pin 6 will also be high and PNP will remain OFF. If the reference voltage at pin 2 is higher than the voltage at pin 3 then PNP will be ON.

- **Zener Diode:**

Zener diode is used as a reference voltage which is 5.1V at inverting pin 2. If the reference voltage on the zener diode is higher than the voltage at pin 3 then PNP will be ON.

- **BJT:**

In the main circuit a PNP transistor is used. If the voltage at non-inverting pin 3 is higher than 5.1V at the reference voltage at pin 2, then the output pin 6 will be high and PNP will remain OFF. So the relay will remain de-energized, as soon as the reference voltage at pin 2 is higher than the voltage at pin 3 then PNP will be ON and the relay will energize.

- **Relay:**

If the PNP does not conduct then the relay (RL1) will remain de-energized and phase will supply power to the load so relay will remain in normally close (N/C) position. As soon as PNP is ON then relay (RL1) will energize and load will be disconnected from phase and connected to the next phase through the next relay (RL2).

### **3.10. Summary**

A very short description of diode, Zener diode, BJT, Op-amp, transformer Relay is given and their specific work in the circuit is also discussed in this chapter. Those devices are very essential parts of the circuit. Capacitor and Resistor are also part of the main circuit but their description is not given in this chapter. This chapter gives the clear idea of what are the main devices used in the main circuit and their work.

## CHAPTER 4

### Simulation and Result

#### 4.1 Introduction

Simulating a circuit behavior before actually building it can greatly improve design efficiency by making faulty designs known as such, and providing insight into the behavior of electronic circuit design. Our Automatic Phase Changer (APC) circuit has been simulated before implementation to see how it may operate and what types of fault may occur in practical hardware level. **Proteus 8 Professional** simulation software is used for simulation here.

#### 4.2 Electronic Simulation Software: *Proteus 8 Professional*

*Proteus* is a software for electronic circuit simulation, schematic capture and printed circuit board (PCB) design. It is developed by *Labcenter Electronics*. *Proteus 8 Professional* version has an enriched component library and many features which help designer to design and analyze a circuit easily. The figure 4.1 below is shows the design procedure of Automatic Phase Changer circuit in *Proteus*. [12]

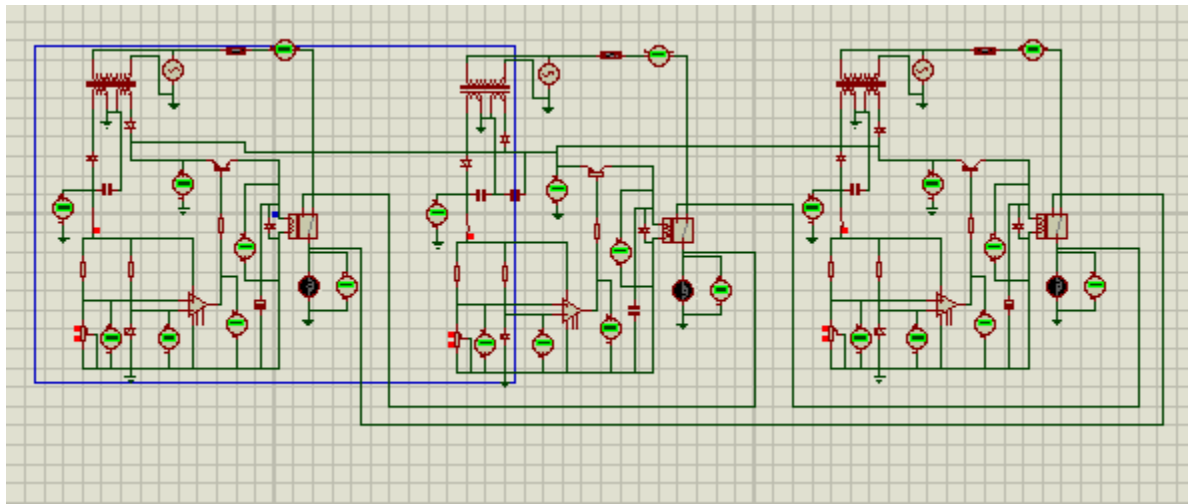


Figure 4. 1: Wiring the Automatic Phase Changer Circuit in *Proteus 8 Professional*.

### 4.3 Simulation of the APC circuit

In the simulation three different ac voltage sources of rating Peak Voltage = 120V, Frequency = 60Hz are used as three phase power supply. Doing this allows to increase or decrease the voltage of any power supply line easily. At the load side three bulbs are used as load for three phase supply. Fuse of current rating 12A is used in each phase as a protective device. Voltmeters and Ammeters are used at the places where it is necessary to take the voltage and current for analysis.

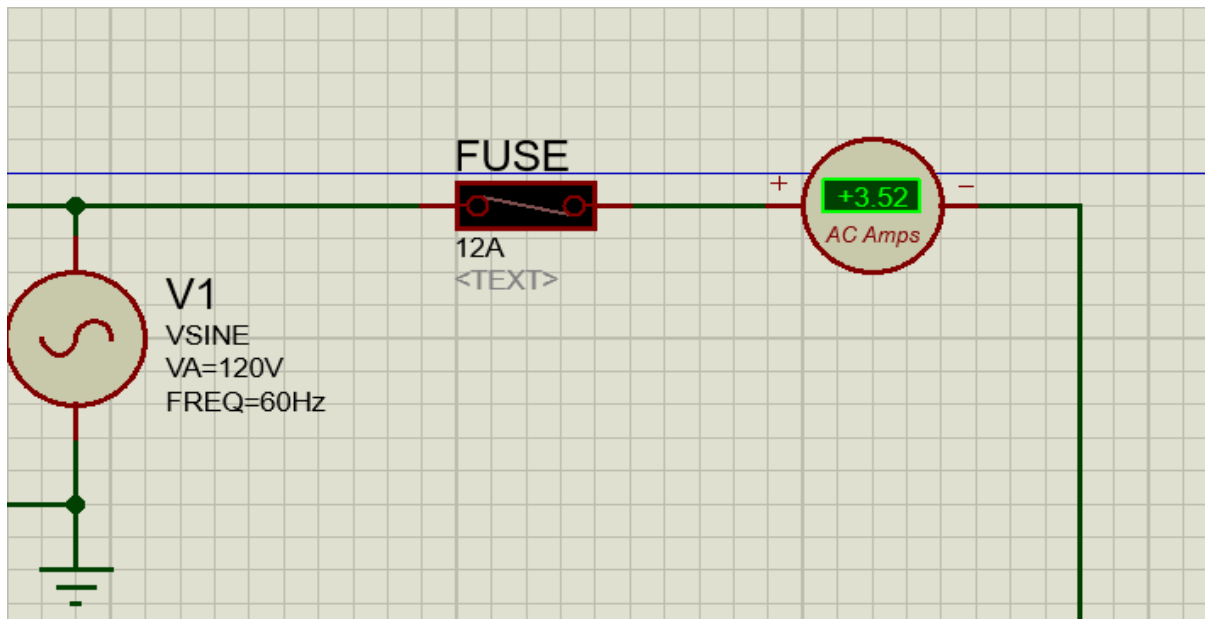
As it is described that this circuit works for single and double phase fault or voltage down the nominal rating at any one or two phases when other phase has correct level of voltage. Therefore, the simulation has been done under three conditions as follows:

- a) All three phases have nominal voltage ratings (120V, 60 Hz)
- b) Any one phase has voltage below the nominal rating (<120V, 60 Hz)
- c) Any two phases have voltage below the nominal rating (<120V, 60 Hz)

In the all three conditions above loads must get correct level of voltages for their perfect operation. But at least one supply line must have nominal voltage to supply correct voltage to the others. The three probable conditions are examined by simulation.

#### 4.3.1 All three phases have nominal voltage ratings (120V, 60 Hz)

When all three power supply lines have correct level of voltage, there is no problem. Then it was obtained 84.6V (rms value of 120V) in the voltmeter across the loads. The figure 4.2 shows the current and voltage ratings at the normal condition for one phase. Other two phases have same ratings as well.





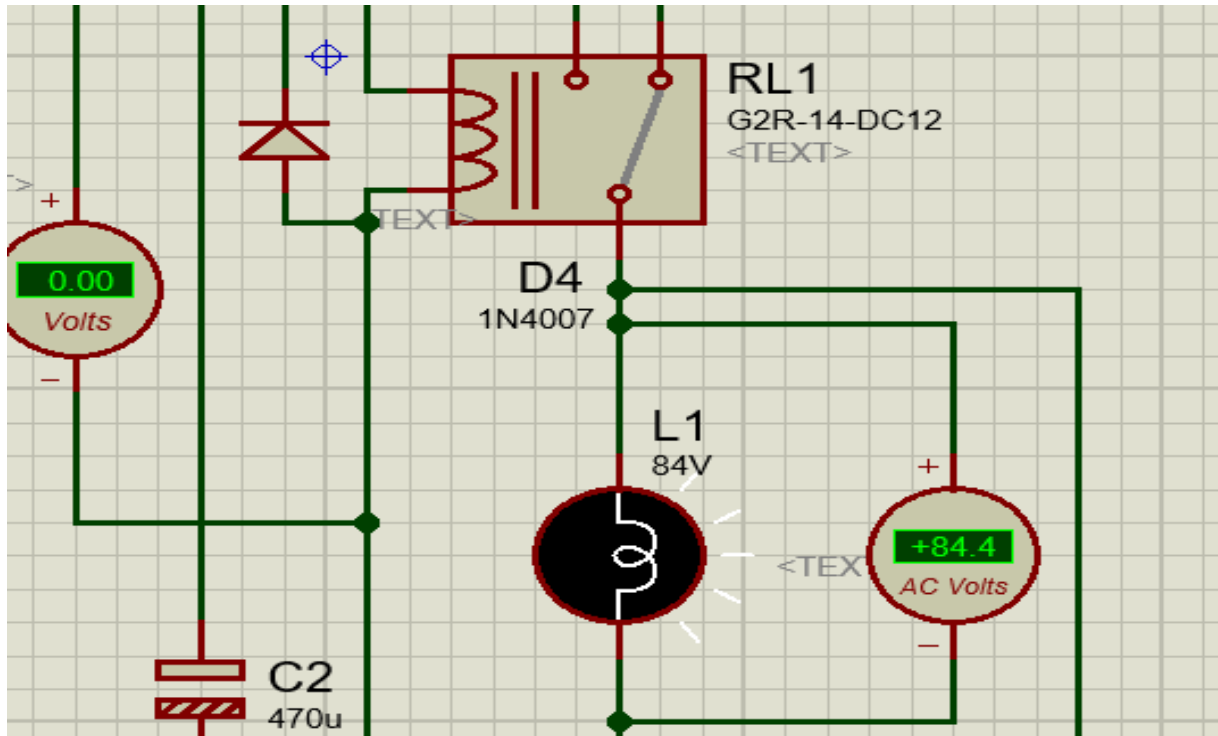


Figure 4. 2: Voltage and current rating for phase – 1 (Upper) and voltage across load – 1 (L1, A bulb) for this phase.

It is seen from the figure 4.2 that in the normal condition each phase carries 3.52A currents for the load of a bulb of 25W. But practically for various devices current rating may vary. Hence, fuse 12A rated fuses have been used.

#### 4.3.2 Any one phase has voltage below the nominal rating (<120V)

Now it will be observed what happens when any of the power supply lines has voltage less than the nominal voltage. For example, in the simulation it was made the voltage of phase-3 117V (<120V). The rms value of 117V is 82.73V, but voltage across the load-3 (L3, A bulb) is still 84.6V which is the rms value of 120V. This implies, the circuit is working properly and load-3 is getting correct voltage level from the healthy power supply line. Figure 4.3 below shows the current through phase-3 and voltage across load-3.

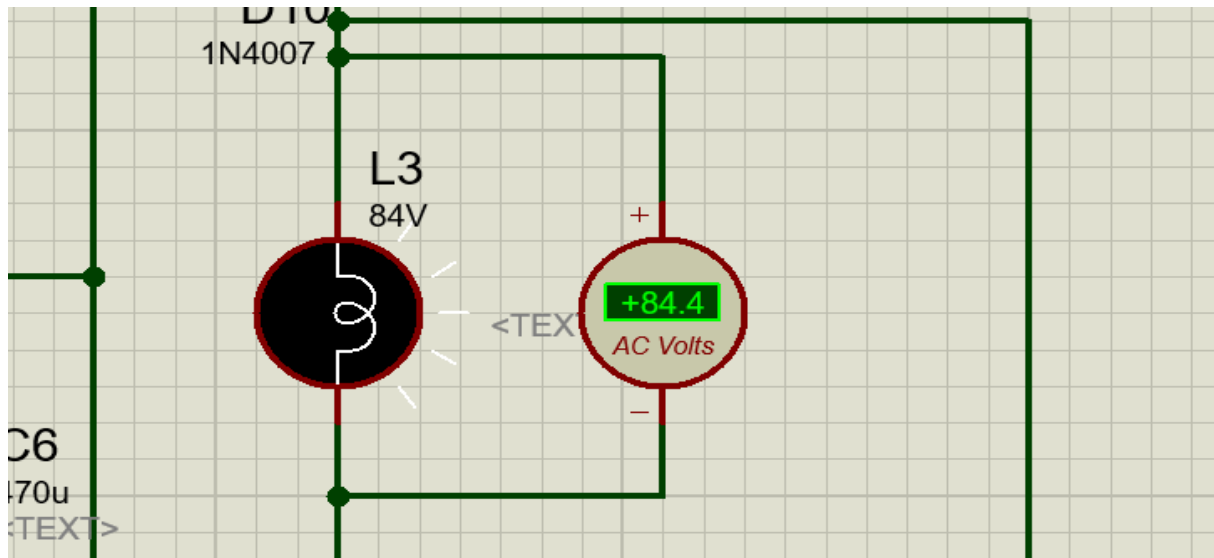
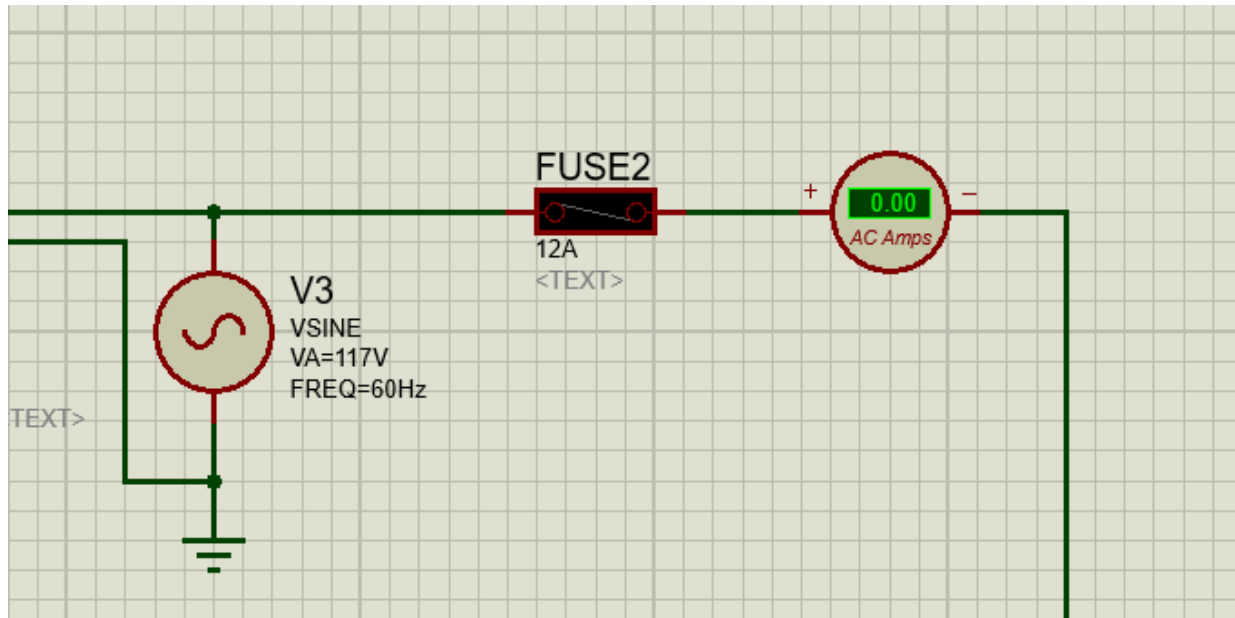


Figure 4. 3: Current through phase-3 when phase voltage is 117V (Upper). Voltage across load-3 (L3, A bulb) is 84.4V (Rms value of 120V) (Lower).

From the figure 4.3 it is observed that the current through the phase-3 is 0A that means the phase is disconnected from the load. The load-3 is now getting correct voltage from phase-1. Since phase-1 is now connected to load-1 as well as load-2 the current through this phase is increased two times the normal current. So in this condition current through phase-1 is 7.04A ( $2 \times 3.52\text{A}$ ). Figure 4.4 shows this in the simulation below.

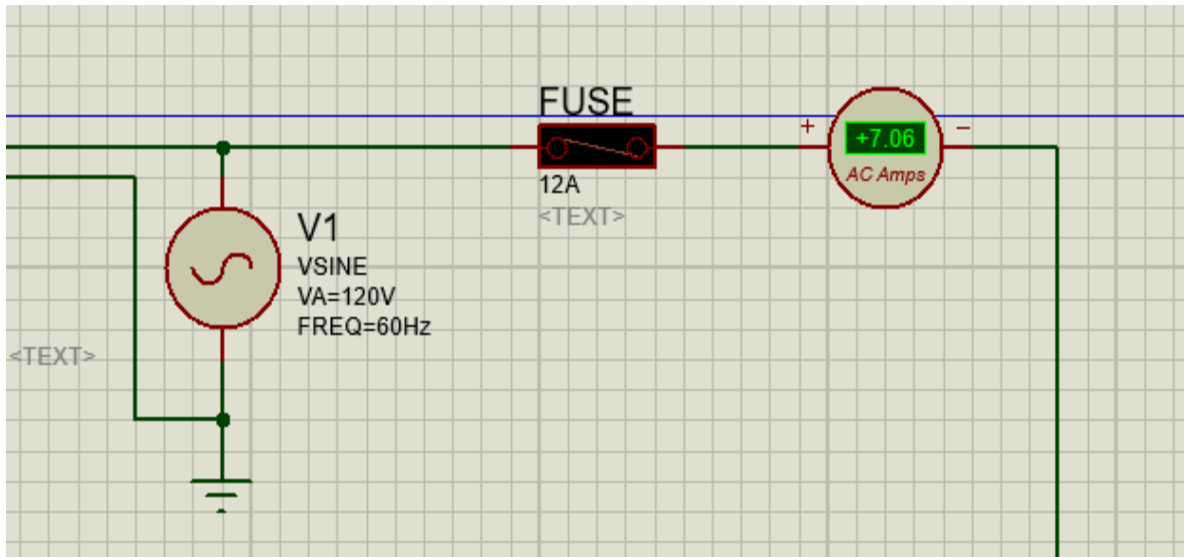


Figure 4. 4: Current through phase-1 is 7.06A ( $2 \times 3.52\text{A}$ ) because this phase also supplies load-3 as well as load-1.

In this case, it is assumed that phase-3 is faulty. But if phase-1 or phase-2 gets affected same result will occur. When phase-1 gets affected it gets correct voltage from phase-2 and when phase-2 gets affected it gets correct voltage from phase-3 as we have seen from the main circuit diagram.

#### 4.3.3 Any two phases have voltage below the nominal rating (<120V)

In this section, it will be examined a case where any two phases have voltage below the nominal rating. Let phase-1 be unaffected and phase-2 & phase-3 have voltage less than 120V (For the simulation, it was made the affected phase voltage 117V). In this situation since phase-2 and phase-3 both are affected, phase-1 carries all currents for three loads. So, Current through phase-1 is 10.5A ( $3 \times 3.52\text{A}$ ). It can be observed from the simulation that all three phases have correct level of voltage under this condition. Therefore, circuit is working properly in simulation. Figure 4.5 to 4.10 show the relevant voltage and current ratings below.

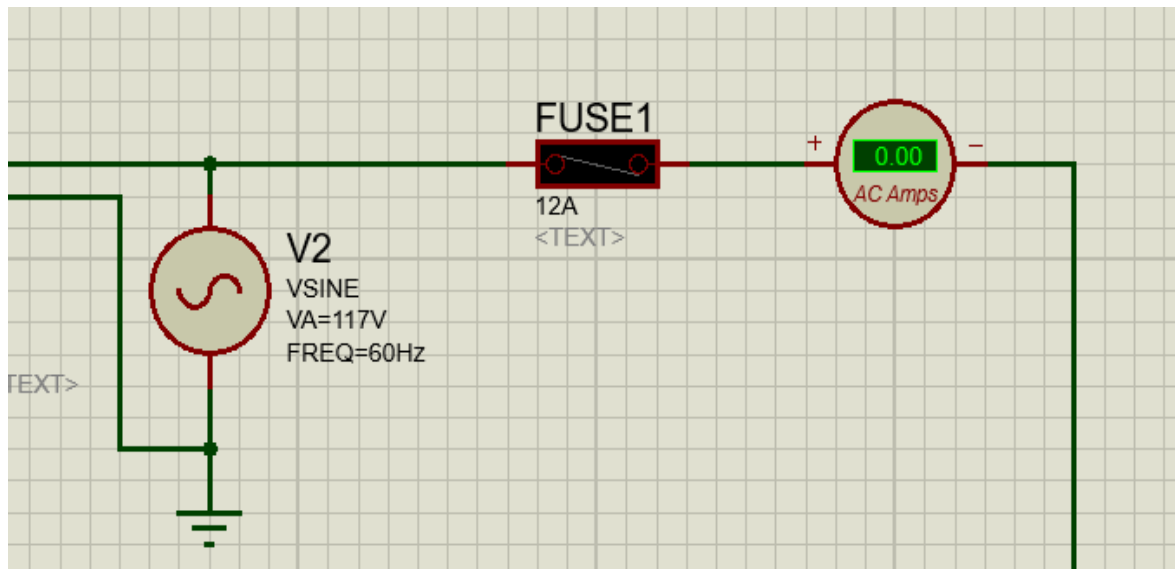


Figure 4. 5: Current through phase-2 is 0A and phase-2 voltage (V2) is 117V.

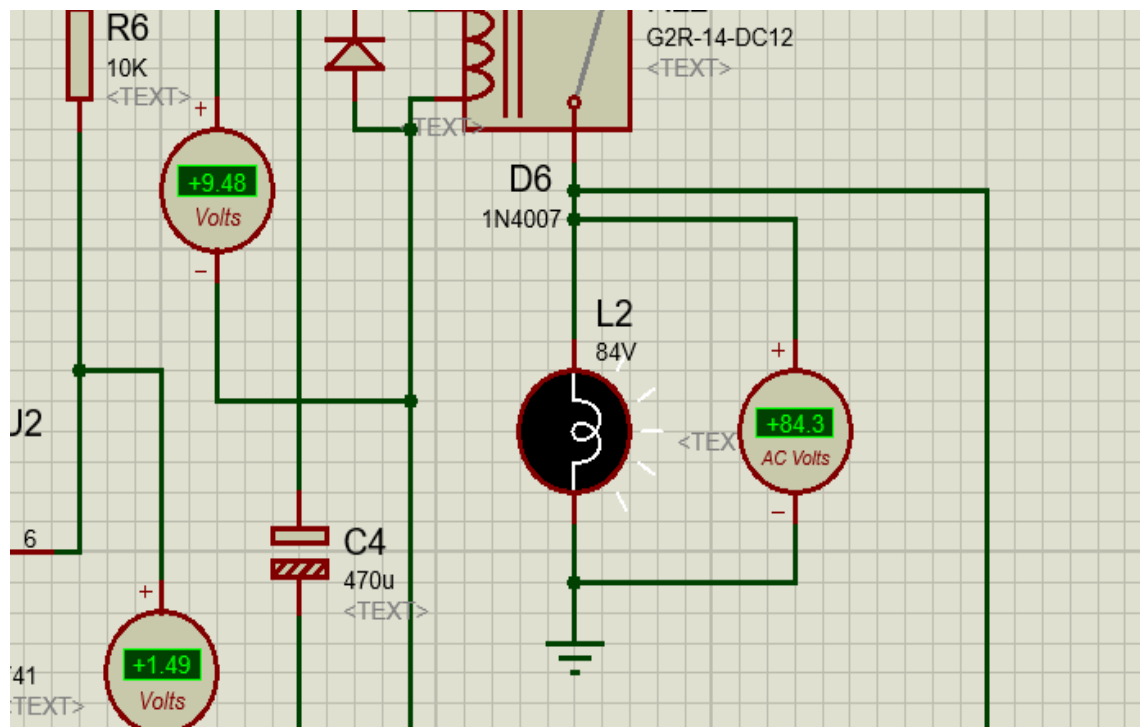


Figure 4. 6: Voltage across load-2 (L2) is 84.3 V (rms value of 120V).

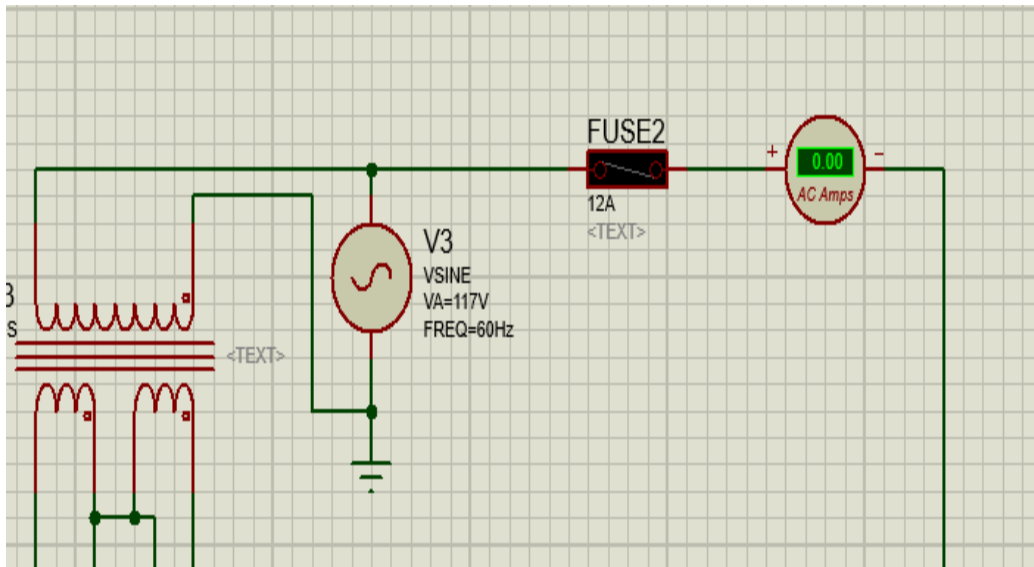


Figure 4. 7: Current of phase-3 is 0A and voltage of phase-3 (V3) is 117V.

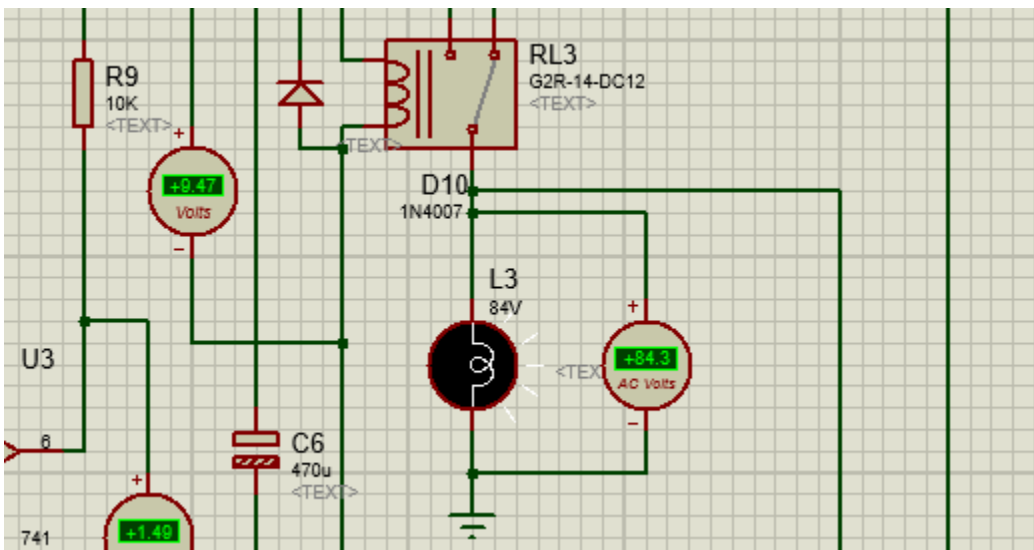


Figure 4. 8: Voltage across load-3 (L3) is 84.3 V (rms value of 120V).

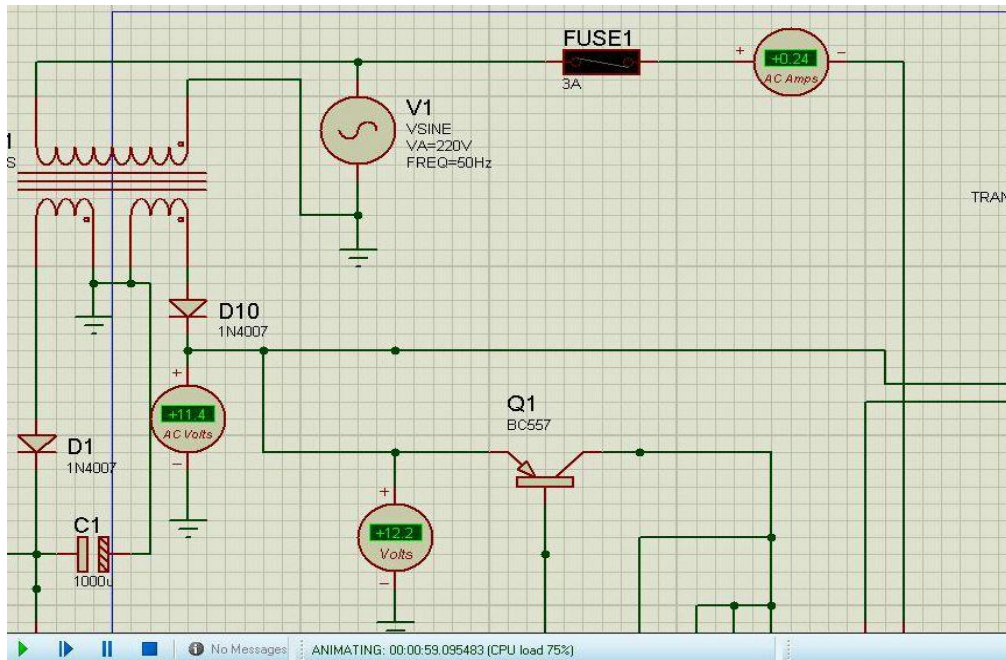


Figure 4. 9: Current through phase-1 is 10.5A and phase-1 voltage (V1) is 120V.

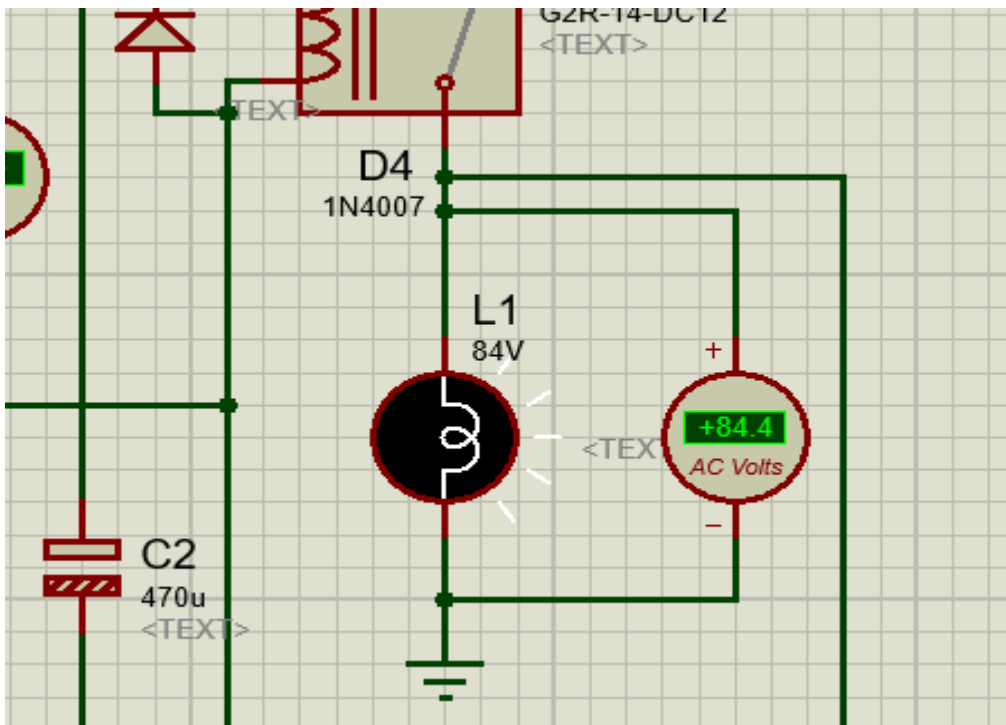


Figure 4. 10: Voltage across load-1 (L1) is 84.4V (Rms value of 120V).

## 4.4 Results of Simulation

The Automatic phase changer circuit may have been observed under three conditions. Results of each condition are given in table 4.1 below. It was selected 117V as the voltage under the nominal voltage of 120V because 117V is the maximum voltage for which the circuit considers the supply line as a faulty line.

Table 4. 1: Results from the simulation for each possible situation.

<b>Situation</b>	<b>Phase</b>	<b>Voltage (V) (RMS Voltage)</b>	<b>Current (A) (For a load of 25W bulb)</b>	<b>Load voltage (V) (RMS)</b>
Normal condition. All the three phases have correct ratings.	Phase-1	120 (84.4)	3.52	84.4
	Phase-2	120 (84.8)	3.52	84.4
	Phase-3	120 (84.8)	3.52	84.4
Phase-3 below 120V	Phase-1	117 (82.7)	0.00	84.4
	Phase-2	120 (84.8)	7.05	84.4
	Phase-3	120 (84.8)	3.52	84.4
Phase-2 & Phase-3 below 120V	Phase-1	120 (84.8)	10.5	84.4
	Phase-2	117 (82.7)	0.00	84.4
	Phase-3	117 (82.7)	0.00	84.4

## **4.5 Summary**

From the table 4.1 of simulation result it is observed that when one or two phases have voltage below 120V the three phase loads always get correct voltages (120V, 84.4V rms) at their terminals if anyone of three phases is healthy. So, three phase loads or the devices which must be connected to correct voltage can be connected to three phase lines through this Automatic Phase Changer circuit. Therefore, it can be said that this simulation is successful.



## **CHAPTER 5**

### **Conclusion and Future Directions**

#### **5.1 Limitation of this study**

- Currently, this circuit is not workable for over voltage protection.
- During under voltage problem any one of the three phase lines takes the loads of another on or two lines. If total power of the loads exceeds the power being supplied from that line, the unnecessary loads needs to be removed from the line. Otherwise voltage may go down further.
- Therefore, for proper working of this circuit without creating any problem in power system, it needs to be used three loads of whose total power demand is less than single phase power capacity.
- This Automatic Phase Changer Circuit works for only emergency loads, which needs almost nominal voltage to operate.

#### **5.2 Conclusions**

The Automatic Phase Changer (APC) is a circuit which changes the phase automatically. Thus it can find its application in household, hospital and even in industry for emergency loads. From simulation, the APC circuit has been observed effective and workable. The simulation was done using Proteus 8 Professional simulation software. Here, it has been used 120V, 60Hz (rms value is 84.8 V) as rated nominal phase voltage. In the simulation, when peak voltage of any phase falls down to 117V or less load of that phase was to be connected to next normal phase by the circuit. The Automatic Phase Changer circuit has some drawbacks as every circuit can have. Otherwise, it is an applicable circuit for the power system. This circuit further can be improved.

### **5.3 Directions for the future work**

This circuit demands future work to improve it. This circuit was made only for under voltage protection. It can also be implemented for over voltage protection. Microcontroller can be used instead of Op-amp which will increase the robustness of the circuit. Now, when under voltage problem occurs only a phase which has normal voltage takes the loads of another one or two phase. This may arise power overloading problem. In future, there is a scope for automatically shedding the unnecessary loads from the working line to be included in this project..

## **Appendix A**

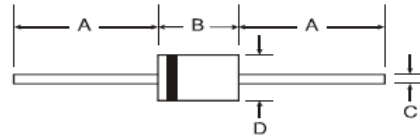
### **Datasheet of the Chips used in the circuit**

## Features

- Diffused Junction
- High Current Capability and Low Forward Voltage Drop
- Surge Overload Rating to 30A Peak
- Low Reverse Leakage Current
- Lead Free Finish, RoHS Compliant (Note 3)

## Mechanical Data

- Case: DO-41
- Case Material: Molded Plastic, UL Flammability Classification Rating 94V-0
- Moisture Sensitivity: Level 1 per J-STD-020D
- Terminals: Finish - Bright Tin, Plated Leads Solderable per MIL-STD-202, Method 208
- Polarity: Cathode Band
- Mounting Position: Any
- Ordering Information: See Page 2
- Marking: Type Number
- Weight: 0.30 grams (approximate)



Dim	DO-41 Plastic	
	Min	Max
A	25.40	—
B	4.06	5.21
C	0.71	0.864
D	2.00	2.72
All Dimensions in mm		

## Maximum Ratings and Electrical Characteristics @T<sub>A</sub> = 25°C unless otherwise specified

Single phase, half wave, 60Hz, resistive or inductive load.  
For capacitive load, derate current by 20%.

Characteristic	Symbol	1N4001	1N4002	1N4003	1N4004	1N4005	1N4006	1N4007	Unit	
Peak Repetitive Reverse Voltage	V <sub>RRM</sub>	50	100	200	400	600	800	1000	V	
Working Peak Reverse Voltage	V <sub>RWM</sub>									
DC Blocking Voltage	V <sub>R</sub>									
RMS Reverse Voltage	V <sub>R(RMS)</sub>	35	70	140	280	420	560	700	V	
Average Rectified Output Current (Note 1) @ T <sub>A</sub> = 75°C	I <sub>O</sub>					1.0				A
Non-Repetitive Peak Forward Surge Current 8.3ms single half sine-wave superimposed on rated load	I <sub>FSM</sub>					30				A
Forward Voltage @ I <sub>F</sub> = 1.0A	V <sub>FM</sub>					1.0				V
Peak Reverse Current @T <sub>A</sub> = 25°C	I <sub>RM</sub>					5.0				μA
at Rated DC Blocking Voltage @ T <sub>A</sub> = 100°C						50				
Typical Junction Capacitance (Note 2)	C <sub>j</sub>	15				8			pF	
Typical Thermal Resistance Junction to Ambient	R <sub>θJA</sub>					100				K/W
Maximum DC Blocking Voltage Temperature	T <sub>A</sub>					+150				°C
Operating and Storage Temperature Range	T <sub>J</sub> , T <sub>STG</sub>					-65 to +150				°C

- Notes:
1. Leads maintained at ambient temperature at a distance of 9.5mm from the case.
  2. Measured at 1.0 MHz and applied reverse voltage of 4.0V DC.
  3. EU Directive 2002/95/EC (RoHS). All applicable RoHS exemptions applied, see EU Directive 2002/95/EC Annex Notes.

# BC556/557/558/559/560

## PNP EPITAXIAL SILICON TRANSISTOR

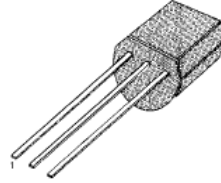
### SWITCHING AND AMPLIFIER

- HIGH VOLTAGE: BC556,  $V_{CE0} = -85V$
- LOW NOISE: BC559, BC560
- Complement to BC546 ... BC 550

### ABSOLUTE MAXIMUM RATINGS ( $T_A = 25^\circ C$ )

Characteristic	Symbol	Rating	Unit
Collector-Base Capacitance : BC556	$V_{CB0}$	-80	V
: BC557/560		-50	V
: BC558/559		-30	V
Collector-Emitter Voltage : BC556	$V_{CE0}$	-85	V
: BC557/560		-45	V
: BC558/559		-30	V
Emitter-Base Voltage	$V_{EB0}$	-5	V
Collector Current (DC)	$I_C$	-100	mA
Collector Dissipation	$P_C$	500	mW
Junction Temperature	$T_J$	150	$^\circ C$
Storage Temperature	$T_{STG}$	-65 ~ 150	$^\circ C$

TO-92



1. Collector 2. Base 3. Emitter

### ELECTRICAL CHARACTERISTICS ( $T_A = 25^\circ C$ )

Characteristic	Symbol	Test Conditions	Min	Typ	Max	Unit
Collector Cut-off Current	$I_{CBO}$	$V_{CE} = -30V, I_B = 0$			-15	nA
DC Current Gain	$h_{FE}$	$V_{CE} = -5V, I_C = 2mA$	110		800	
Collector Emitter Saturation Voltage	$V_{CE(sat)}$	$I_C = -10mA, I_B = -0.5mA$		-90	-300	mV
		$I_C = -100mA, I_B = -5mA$		-250	-650	mV
Collector Base Saturation Voltage	$V_{BE(on)}$	$I_C = -10mA, I_B = -0.5mA$		-700		mV
		$I_C = -100mA, I_B = -5mA$		-900		mV
Base Emitter On Voltage	$V_{BE(on)}$	$V_{CE} = -5V, I_C = -2mA$	-800	-860	-750	mV
		$V_{CE} = -5V, I_C = -10mA$		-800		mV
Current Gain Bandwidth Product	$f_T$	$V_{CE} = -5V, I_C = -10mA$		150		MHz
Collector Base Capacitance	$C_{CB0}$	$V_{CE} = -10V, f = 1MHz$			6	pF
Noise Figure	NF	$V_{CE} = -5V, I_C = -200\mu A$		2	10	dB
: BC556/557/558		$f = 1KHz, R_G = 2K\Omega$		1	4	dB
: BC559/560		$V_{CE} = -5V, I_C = -200\mu A$		1.2	4	dB
: BC559		$R_G = 2K\Omega$		1.2	2	dB
: BC560		$f = 30 \sim 15000MHz$				

### $h_{FE}$ CLASSIFICATION

Classification	A	B	C
$h_{FE}$	110-220	200-450	420-800



## UA741

### GENERAL PURPOSE SINGLE OPERATIONAL AMPLIFIER

- LARGE INPUT VOLTAGE RANGE
- NO LATCH-UP
- HIGH GAIN
- SHORT-CIRCUIT PROTECTION
- NO FREQUENCY COMPENSATION
- REQUIRED
- SAME PIN CONFIGURATION AS THE UA709

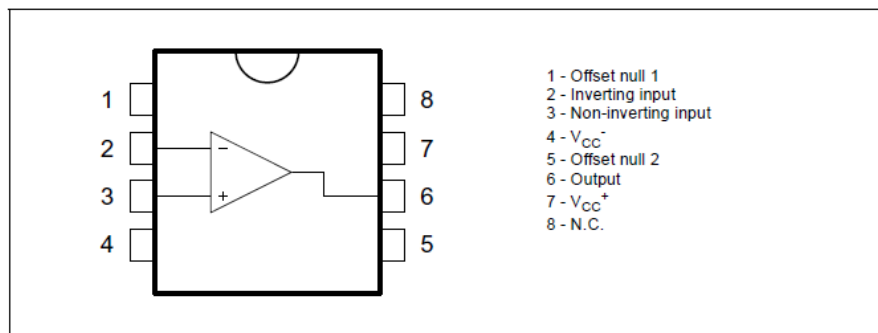
#### DESCRIPTION

The UA741 is a high performance monolithic operational amplifier constructed on a single silicon chip. It is intended for a wide range of analog applications.

- Summing amplifier
- Voltage follower
- Integrator
- Active filter
- Function generator

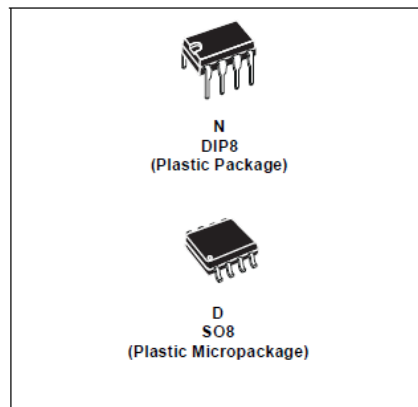
The high gain and wide range of operating voltages provide superior performances in integrator, summing amplifier and general feedback applications. The internal compensation network (6dB/octave) insures stability in closed loop circuits.

#### PIN CONNECTIONS (top view)



November 2001

1/5

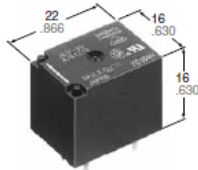


#### ORDER CODE

Part Number	Temperature Range	Package	
		N	D
UA741C	0°C, +70°C	•	•
UA741I	-40°C, +105°C	•	•
UA741M	-55°C, +125°C	•	•

Example : UA741CN

N = Dual in Line Package (DIP)  
D = Small Outline Package (SO) - also available in Tape & Reel (DT)



mm inch

RoHS Directive compatibility information  
<http://www.nais-e.com/>

## FEATURES

- Miniature size with universal terminal footprint
- High contact capacity: 10 A
- TV-5 type available (Standard type)  
1 Form A type → TV-5  
1 Form C type → TV-5 (N.O. side only)
- VDE, TÜV also approved
- Sealed construction for automatic cleaning (Standard type)
- Class B and F coil insulation type also available.
- EN60335-1 GWT compliant (Tested by VDE) type available
- Surge voltage 6 kV type also available

## About Cd-free contacts

We have introduced Cadmium free type products to reduce Environmental Hazardous Substances.  
(The suffix "F" should be added to the part number)  
Please replace parts containing Cadmium with Cadmium-free products and evaluate them with your actual application before use because the life of a relay depends on the contact material and load.

## SPECIFICATIONS

### Contact

Types		Standard type	Long endurance type
Arrangement		1 Form A, 1 Form C	1 Form A
Initial contact resistance, max. (By voltage drop 6 V DC 1 A)		100 mΩ	
Contact material		AgSnO <sub>2</sub> type	
Rating (resistive load)	Nominal switching capacity	10 A 250 V AC 10 A 125 V AC 6 A 277 V AC	10 A 250 V AC 10 A 125 V AC 10 A 277 V AC
	Max. switching power	2,500 VA	
	Max. switching voltage	250 V AC, 100 V DC	
	Max. switching current	10 A (AC), 5 A (DC)	
	Min. switching capacity*1	100 mA, 5 V DC	
Expected life (min. ope.)	Mechanical (at 180 cpm)	10 <sup>7</sup>	
	Electrical at 10 A 125 V AC, 6 A 277 V AC resistive (standard) 10 A 277 V AC resistive (High power)	1×10 <sup>6</sup>	2×10 <sup>6</sup>
	10 A 250 V AC resistive (Standard: at 20 cpm) (High power: at 20 cpm, 105°C 221°F)**	5 × 10 <sup>4</sup> (No contact only)	1.2 × 10 <sup>5</sup>

\*\* Holding voltage should be 60% V of nominal voltage

### Coil

Nominal operating power	360 mW
-------------------------	--------

#1 This value can change due to the switching frequency, environmental conditions, and desired reliability level, therefore it is recommended to check this with the actual load.

### Remarks

\*1 Detection current: 10mA

\*2 Excluding contact bounce time

### Characteristics

Max. operating speed	20 cpm	
Types	Standard type	Long endurance type
Initial insulation resistance	Min. 100 MΩ (at 500 V DC)	
Initial breakdown voltage*1	Between open contacts	750 Vrms for 1 min.
	Between contacts and coil	1,500 Vrms for 1 min.
Operate time*2 (at nominal voltage)	Max. 10 ms	
Release time (without diode)*2 (at nominal voltage)	Max. 10 ms	
Temperature rise (at nominal voltage)	Max. 35°C, resistive, nominal voltage applied to coil. Contact carrying current: 10A, at 70°C 158°F	
Shock resistance	Functional*3	98 m/s <sup>2</sup> {10 G}
	Destructive*4	980 m/s <sup>2</sup> {100 G}
Vibration resistance	Functional*5	10 to 55 Hz at double amplitude of 1.6 mm
	Destructive	10 to 55 Hz at double amplitude of 2 mm
Conditions for operation, transport and storage*6 (Not freezing and condensing at low temperature)	Ambient temp.*7	-40°C to +85°C -40°F to +185°F
	Humidity	5 to 85% R.H.
Unit weight	Approx. 12 g .423 oz	

\*3 Half-wave pulse of sine wave: 11ms; detection time: 10μs

\*4 Half-wave pulse of sine wave: 6ms

\*5 Detection time: 10μs

\*6 Refer to 6. Conditions for operation, transport and storage mentioned in

AMBIENT ENVIRONMENT

\*7 When using relays in a high ambient temperature, consider the pick-up voltage rise due to the high temperature (a rise of approx. 0.4% V for each 1°C 33.8°F with 20°C 68°F as a reference) and use a coil impressed voltage that is within the maximum allowable voltage range.

## TYPICAL APPLICATIONS

1. Home appliances  
Air conditioner, heater, etc.
2. Automotive  
Power-window, car antenna, door-lock, etc.
3. Office machines  
PPC, facsimile, etc.
4. Vending machines

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